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van der Burg et al.

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(54) **INSERTION TOOL FOR KNOTLESS SUTURE ANCHOR FOR SOFT TISSUE REPAIR AND METHOD OF USE**

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CPC **A61B 17/0401** (2013.01); **A61B 17/888** (2013.01); **A61B 17/8888** (2013.01); **A61B 2017/00986** (2013.01); **A61B 2017/0404** (2013.01); **A61B 2017/045** (2013.01); **A61B 2017/0409** (2013.01); **A61B 2017/0414** (2013.01); **A61B 2017/0451** (2013.01);
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(58) **Field of Classification Search**
CPC A61B 17/8888; A61B 17/8891; A61B 17/0401; A61B 2017/0409; A61B 2017/0414; A61B 2017/045; A61B 2017/0451; A61F 2002/0858; A61F 2002/0888
USPC 606/139, 142, 143, 232, 300, 318
See application file for complete search history.

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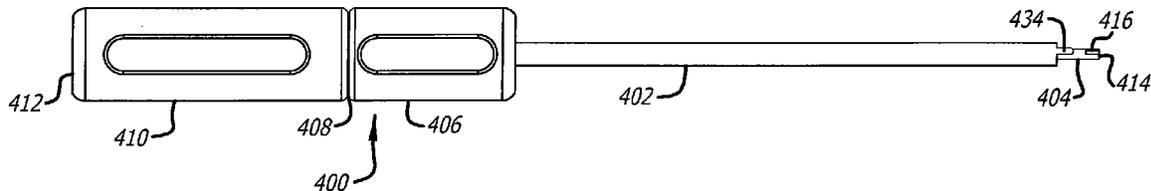
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(57) **ABSTRACT**

An insertion tool is used to implant a knotless suture anchor to secure soft tissue to a rigid structure such as bone. The anchor has an inner member that receives suture thread and rotates within an outer tubular member. An inner shaft on the insertion tool engages the inner tubular member and is used to rotate the inner tubular member so that the suture thread is wrapped onto the inner tubular member thereby increasing contact with the outer tubular member of the anchor which applies pressure to the wrapped suture thread to retain it in position on the inner tubular member while simultaneously and adjustably tensioning the suture thread. The insertion tool has an outer shaft that engages the outer tubular member of the anchor and prevents the outer tubular member from rotating as the inner shaft on the insertion tool rotates the inner tubular member on the anchor.

12 Claims, 22 Drawing Sheets



(51) **Int. Cl.**
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A61F 2/08 (2006.01)

(52) **U.S. Cl.**
 CPC *A61F2002/0858* (2013.01); *A61F 2002/0888* (2013.01)

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FIG. 1
(Prior Art)

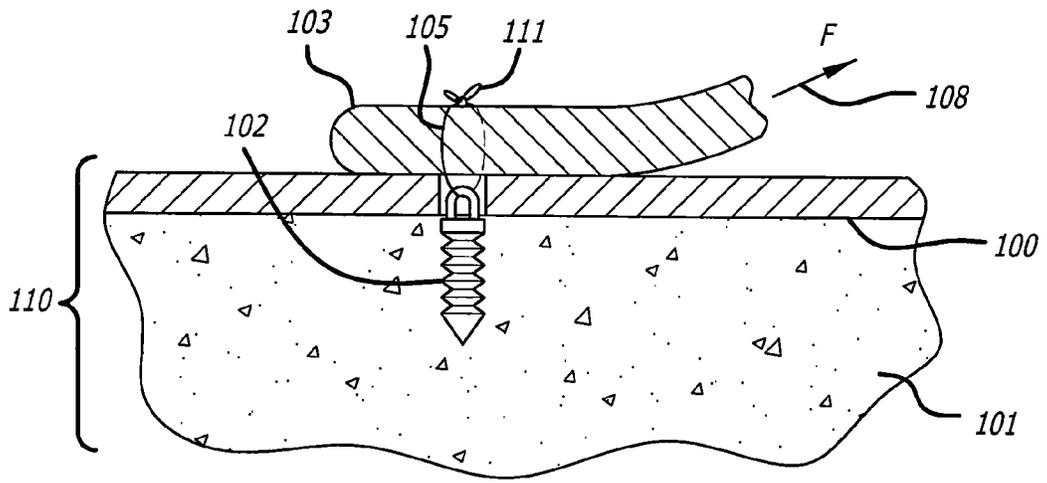
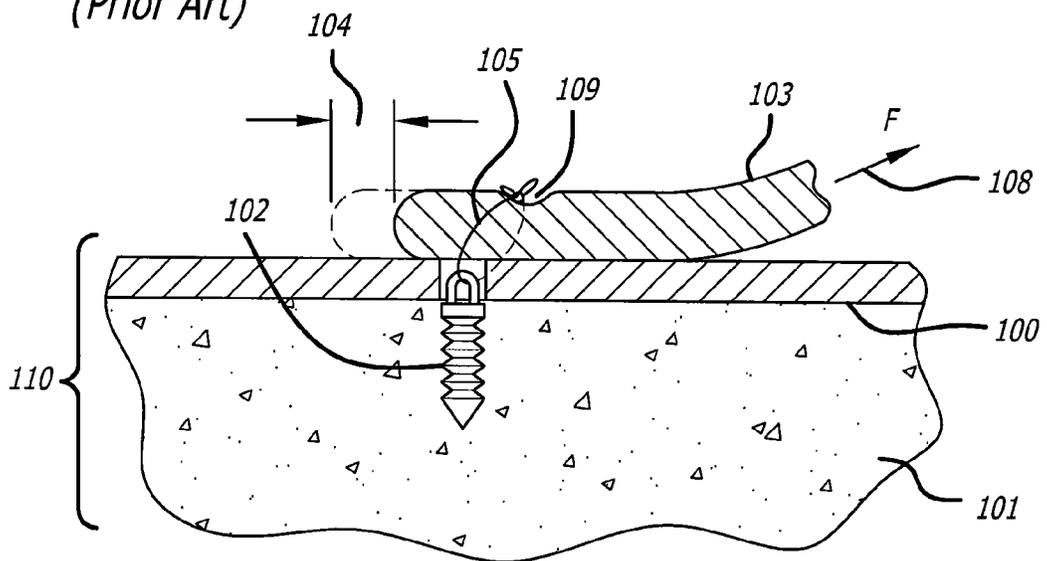
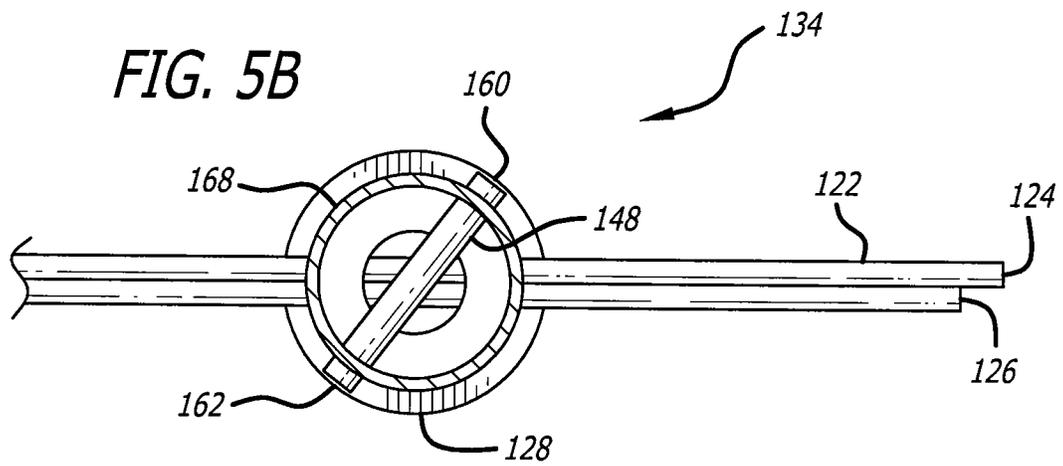
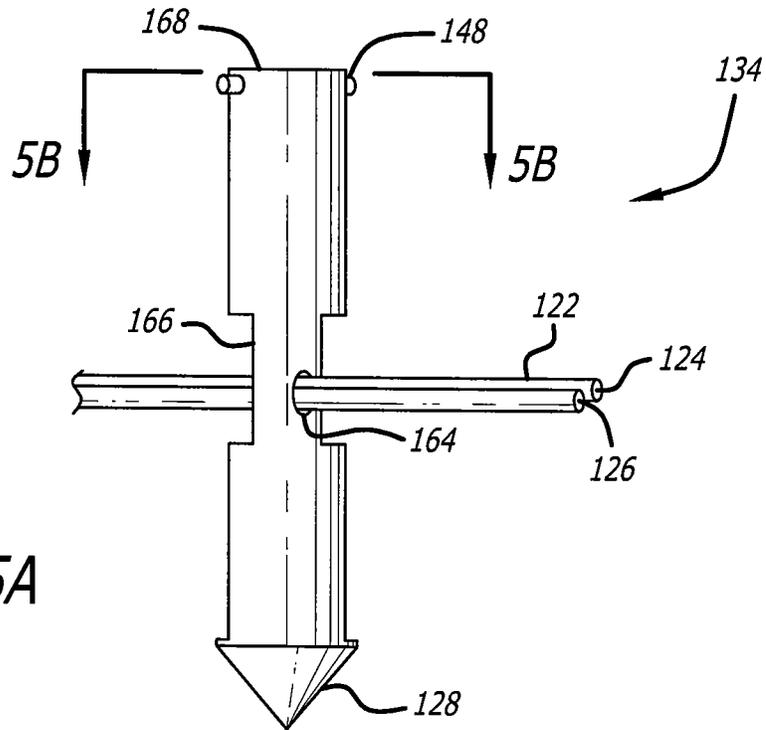


FIG. 2
(Prior Art)





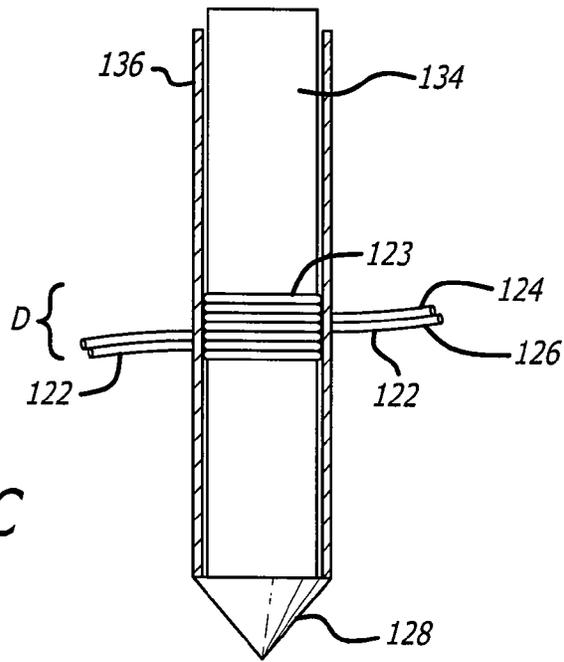


FIG. 5C

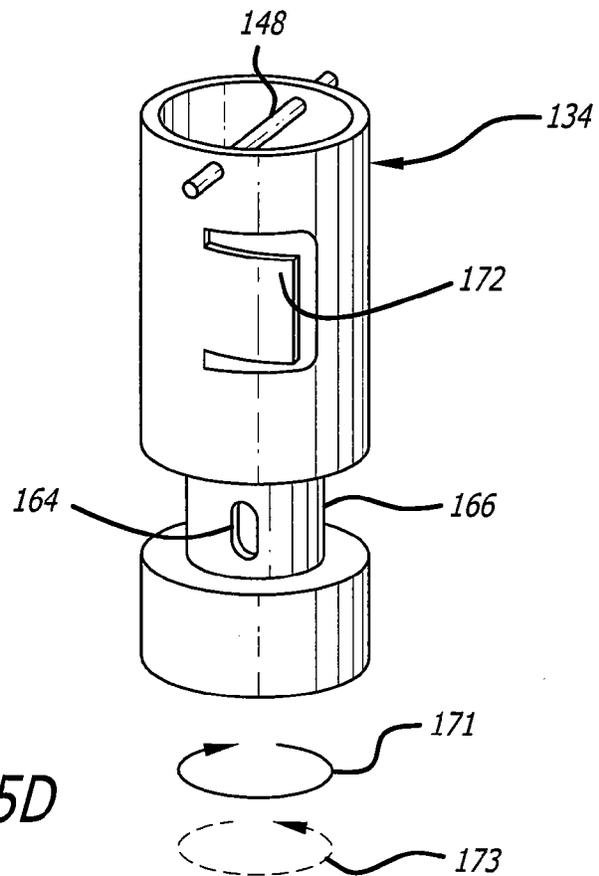


FIG. 5D

FIG. 5E

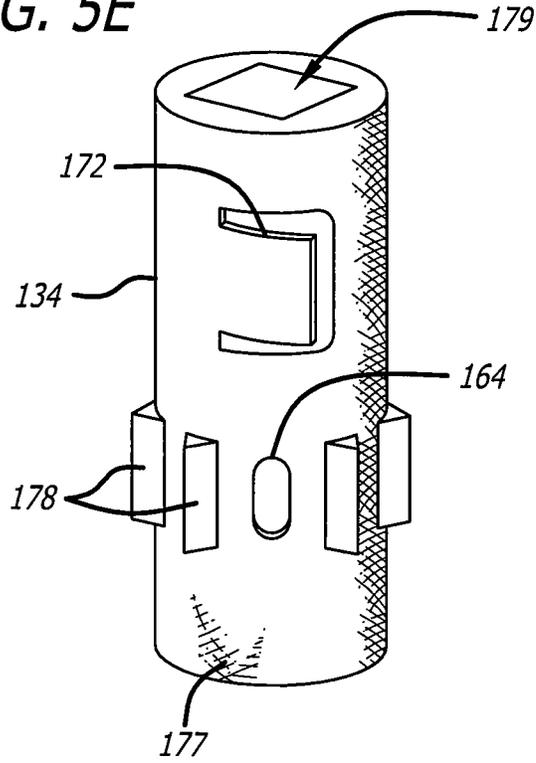


FIG. 5F

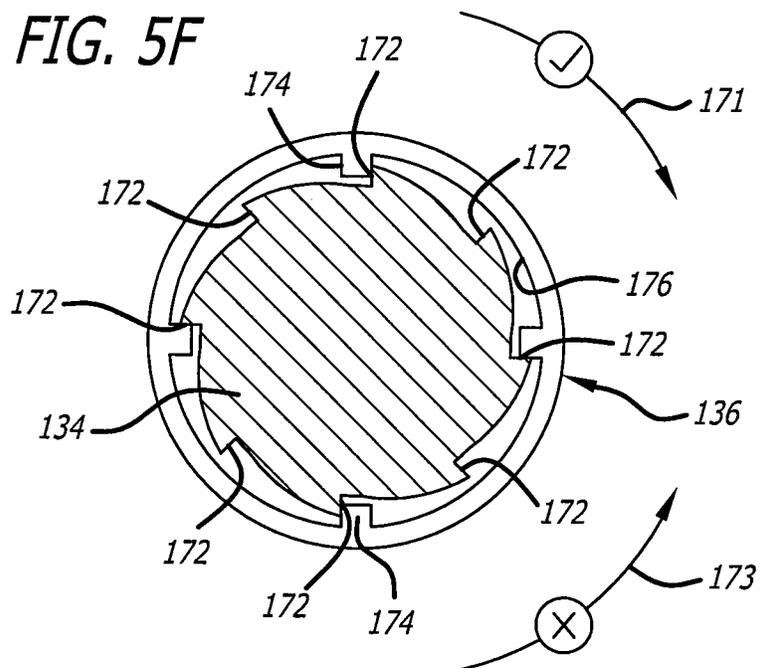


FIG. 6A

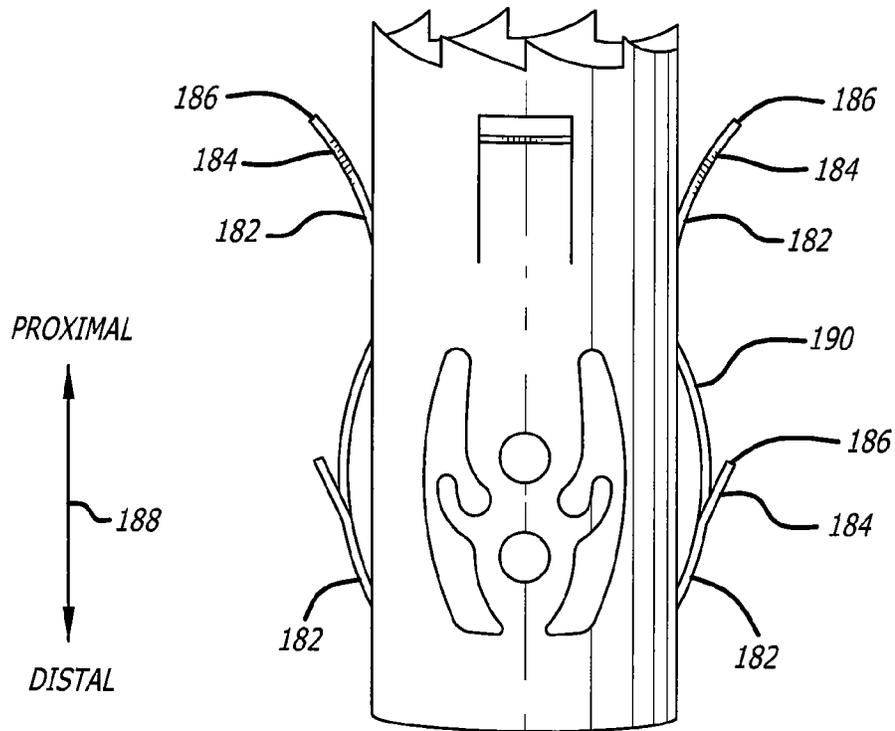


FIG. 6B

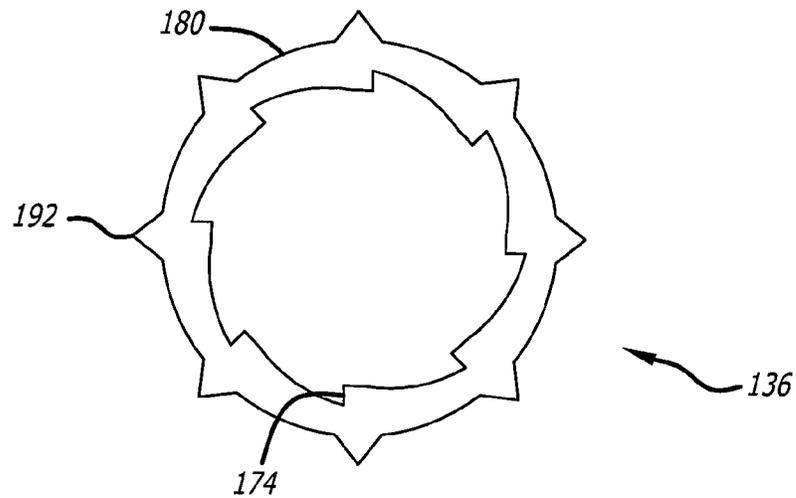


FIG. 7

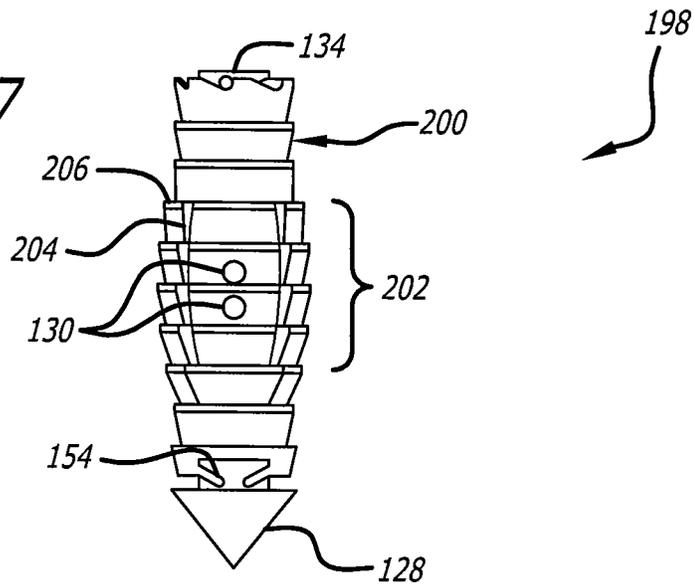


FIG. 8

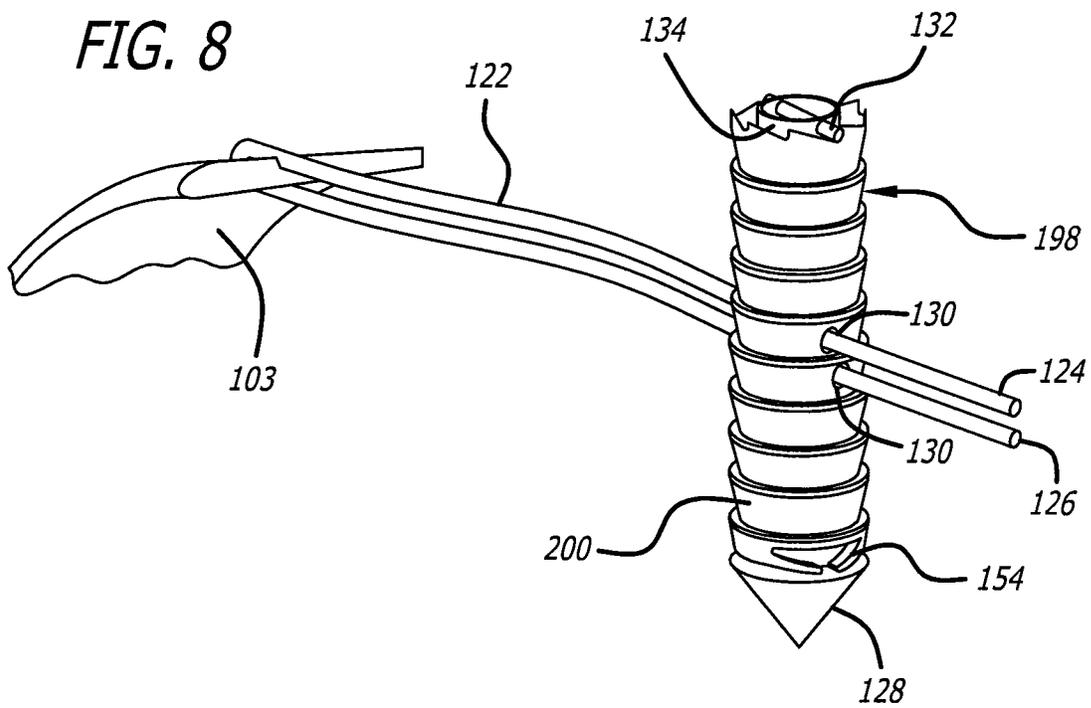


FIG. 9

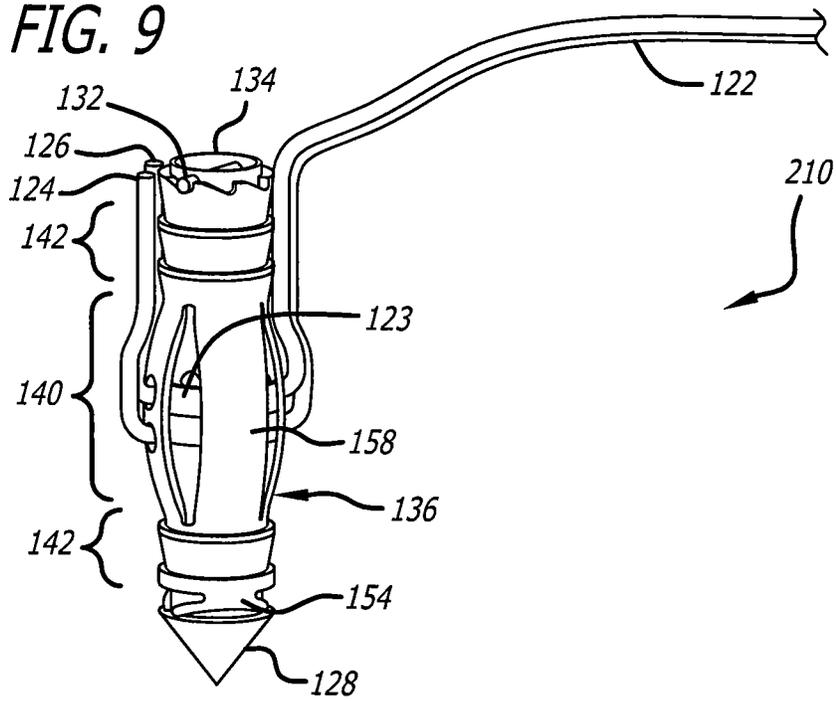
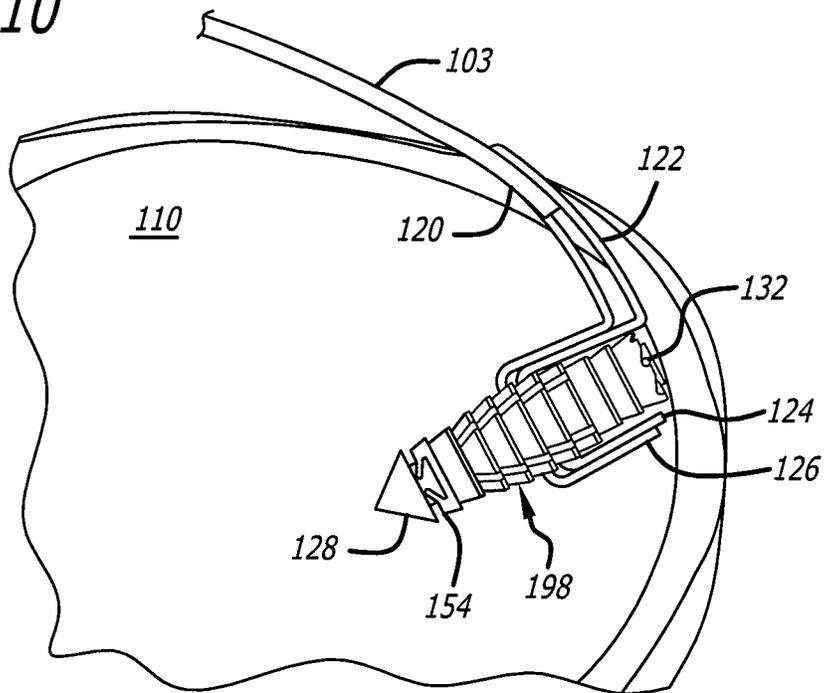
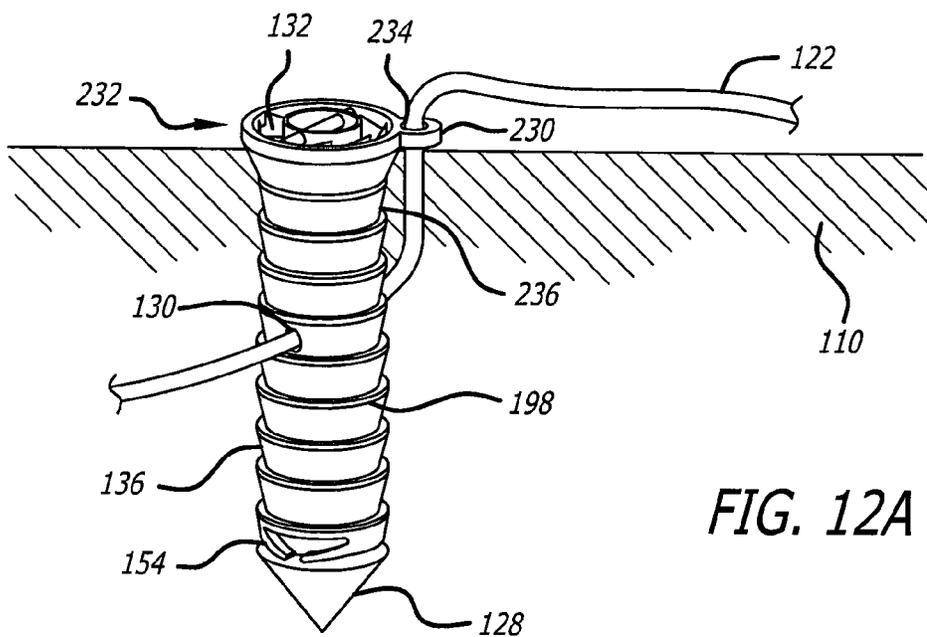
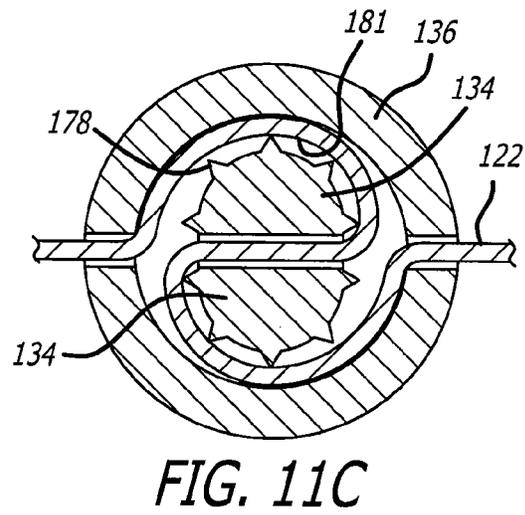
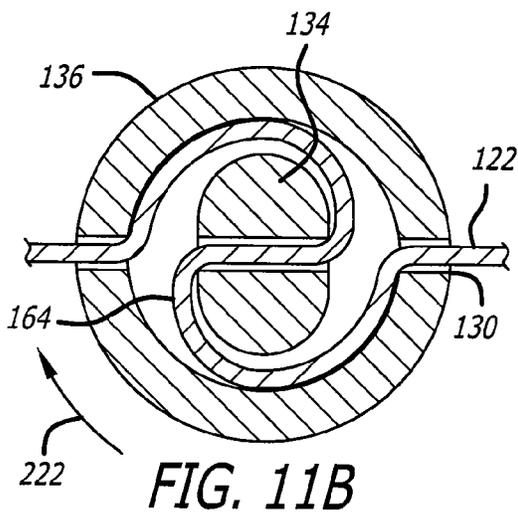
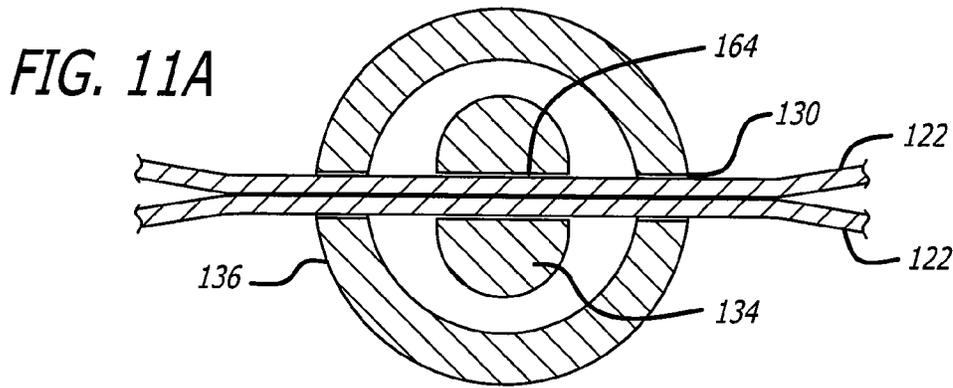


FIG. 10





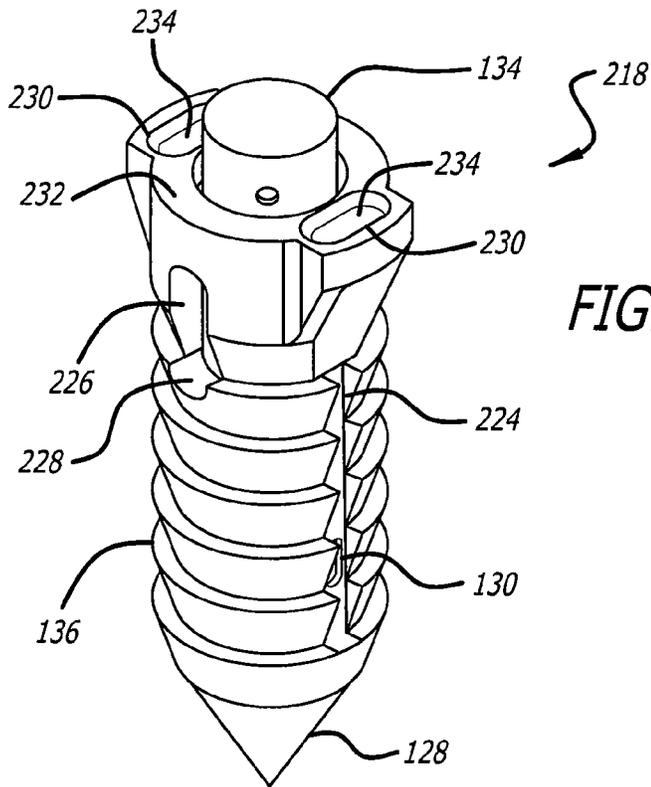


FIG. 12B

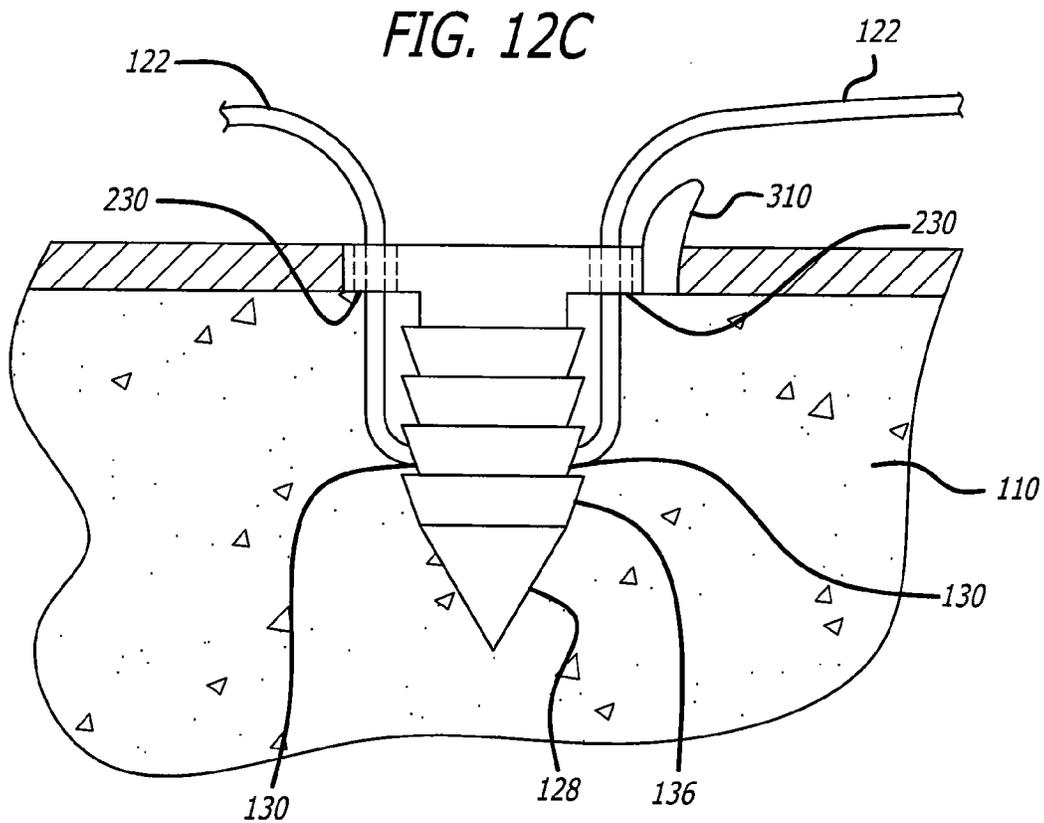


FIG. 12C

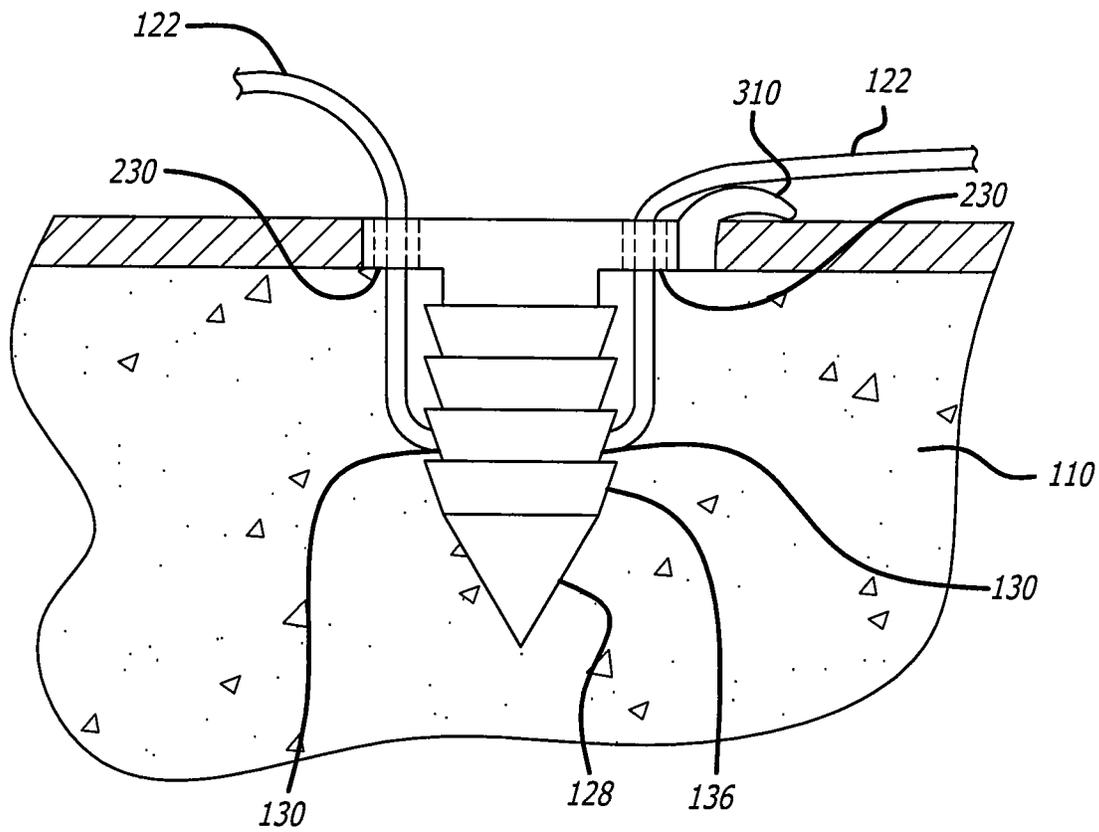
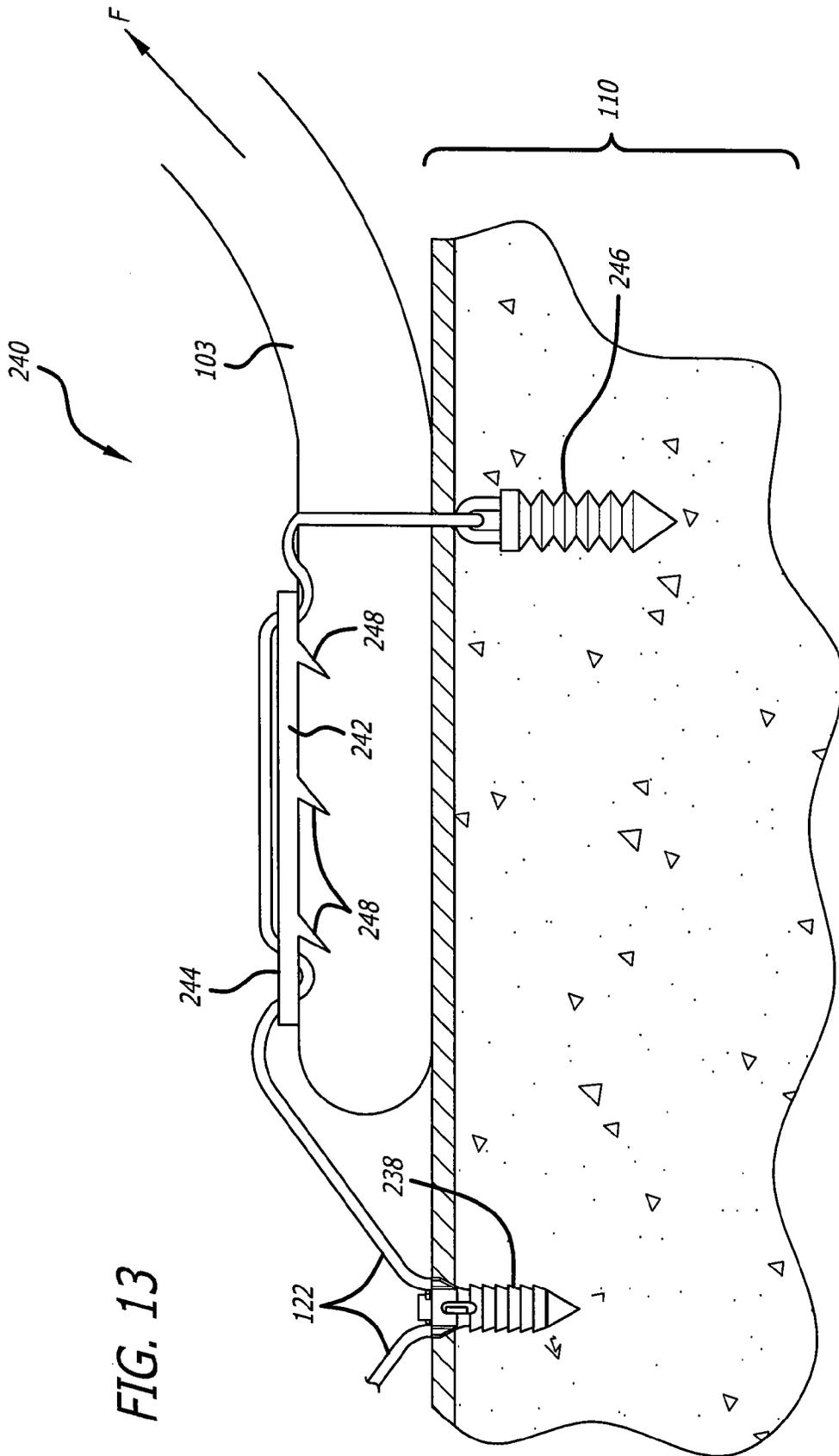
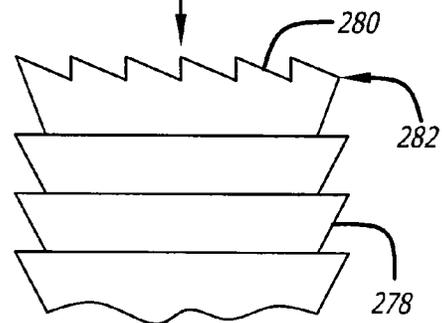
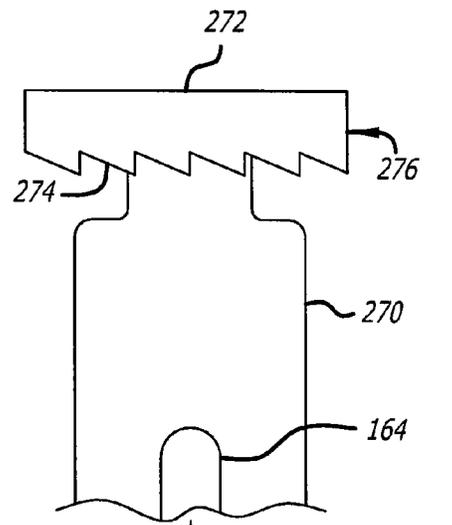
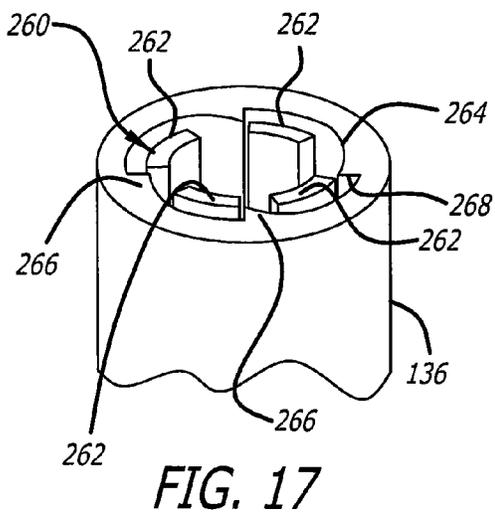
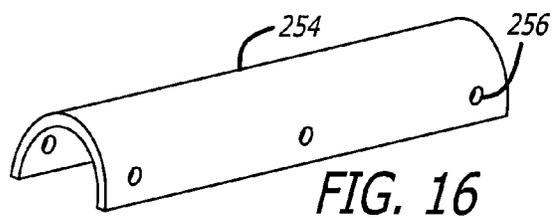
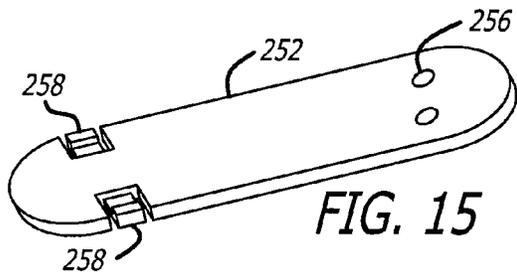
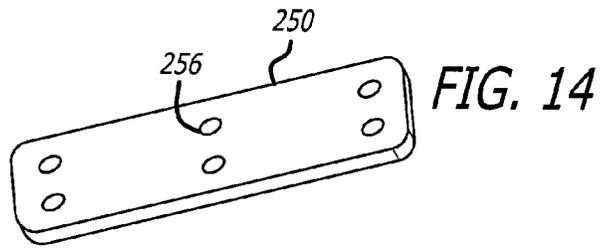
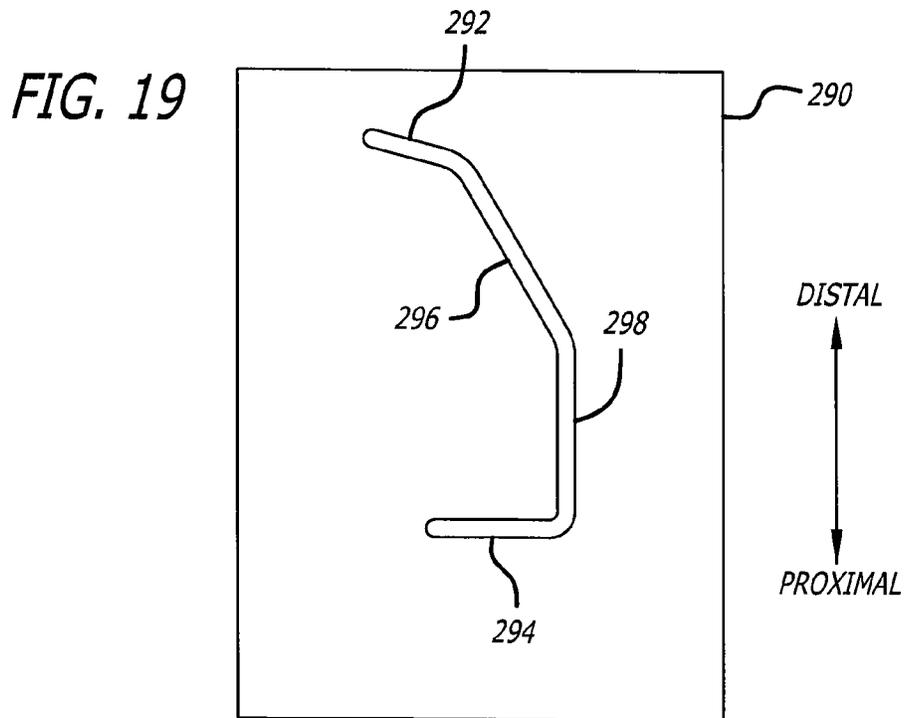
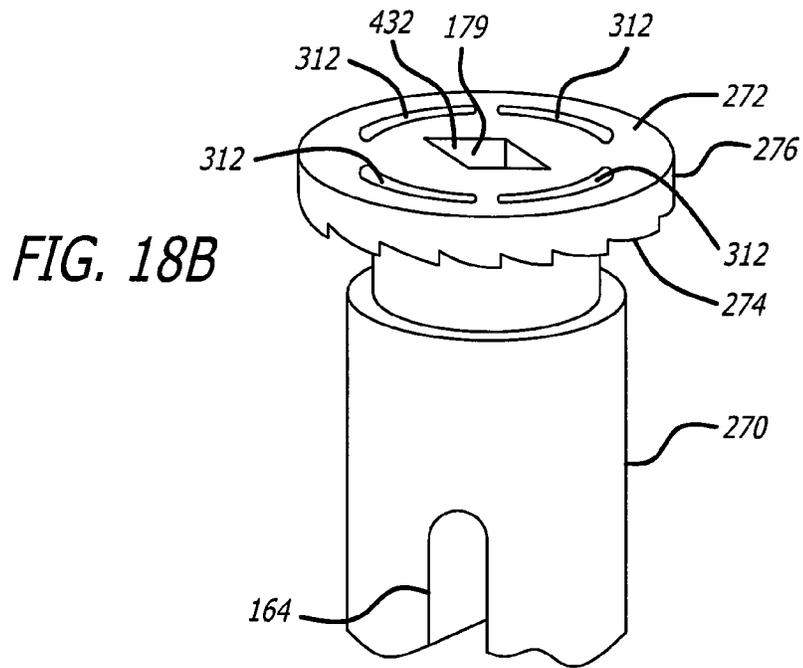


FIG. 12D







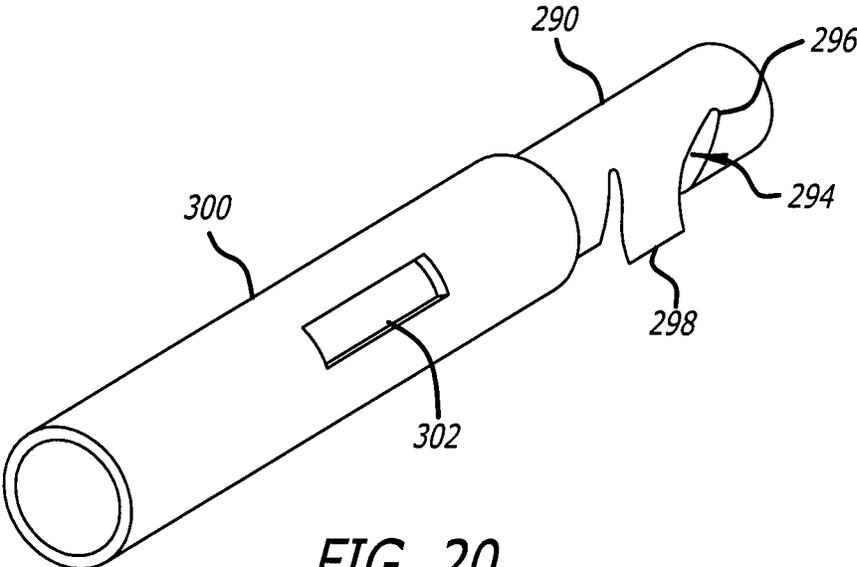
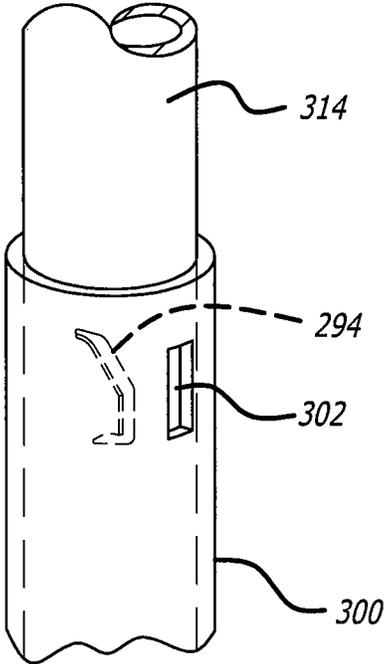
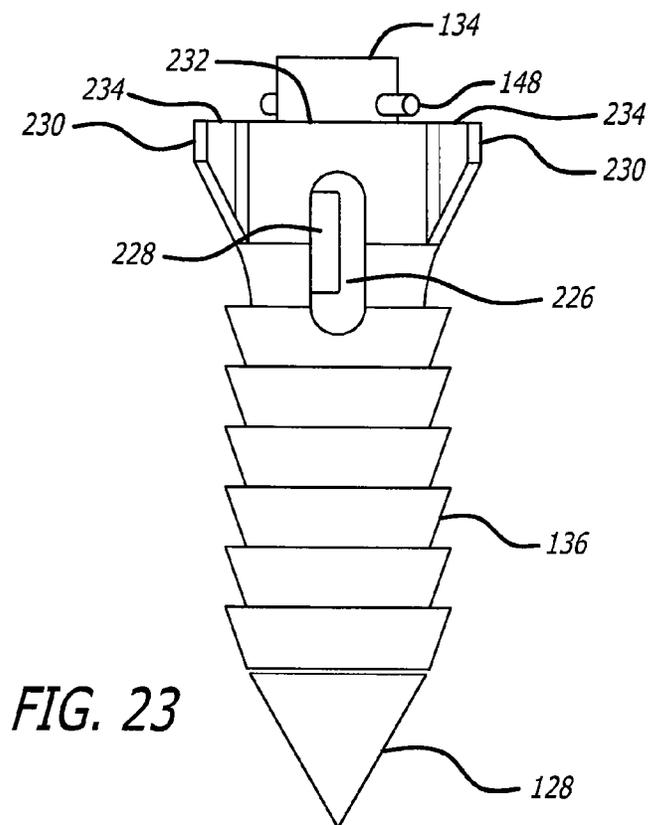
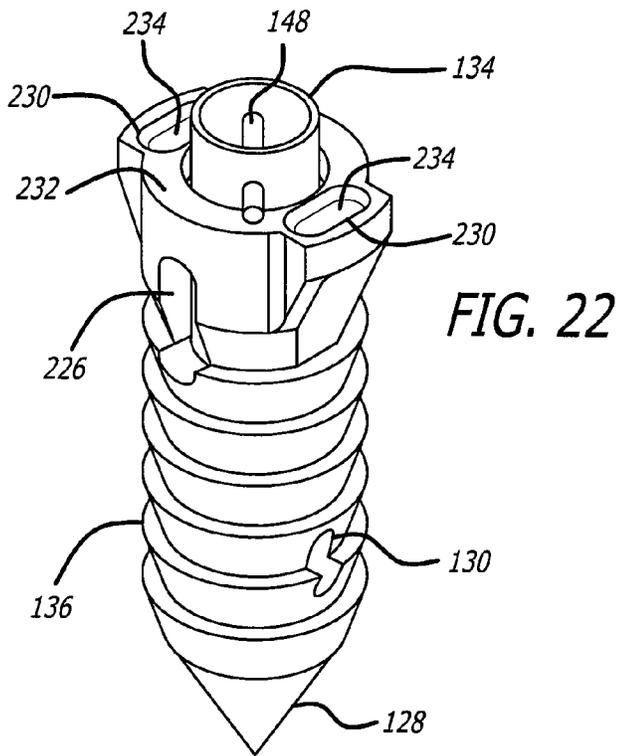
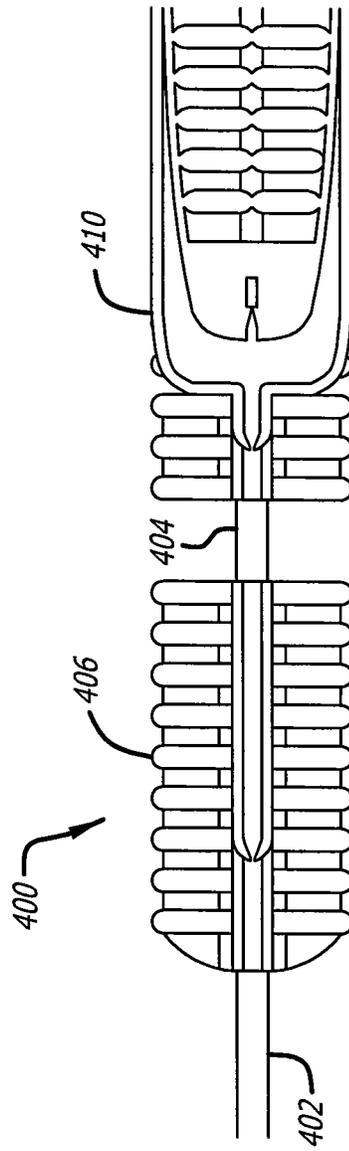
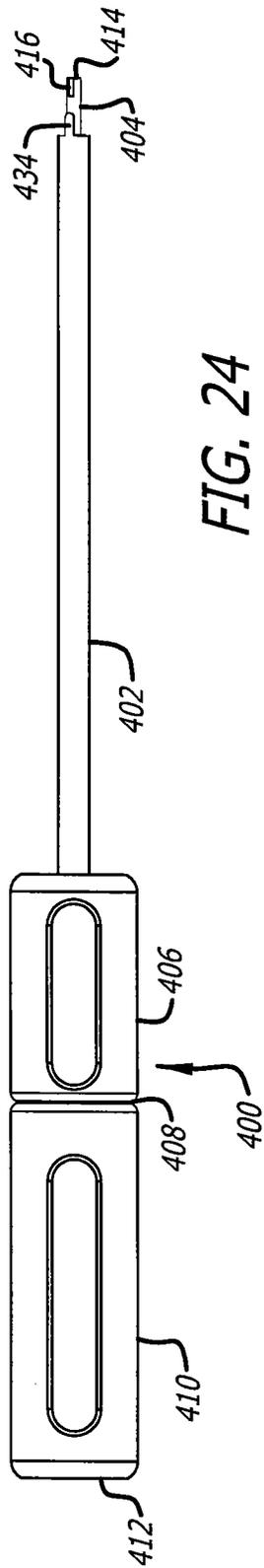


FIG. 21







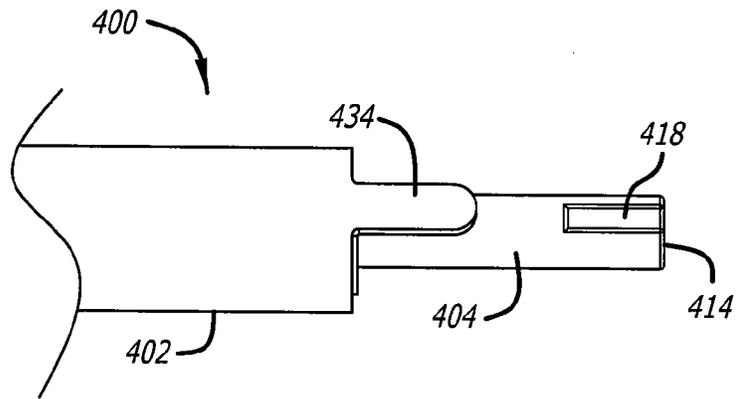


FIG. 26A

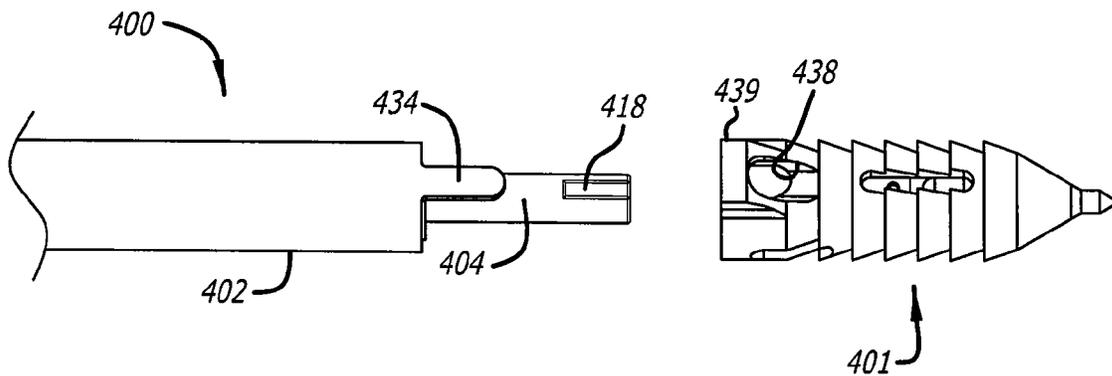
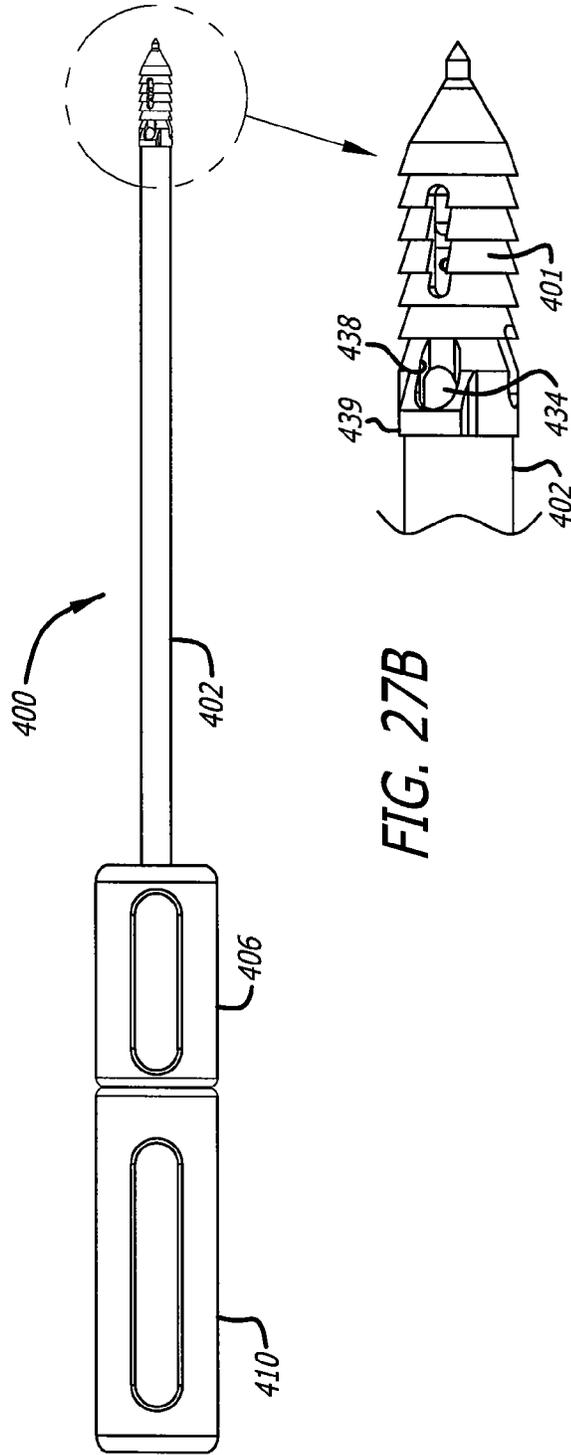
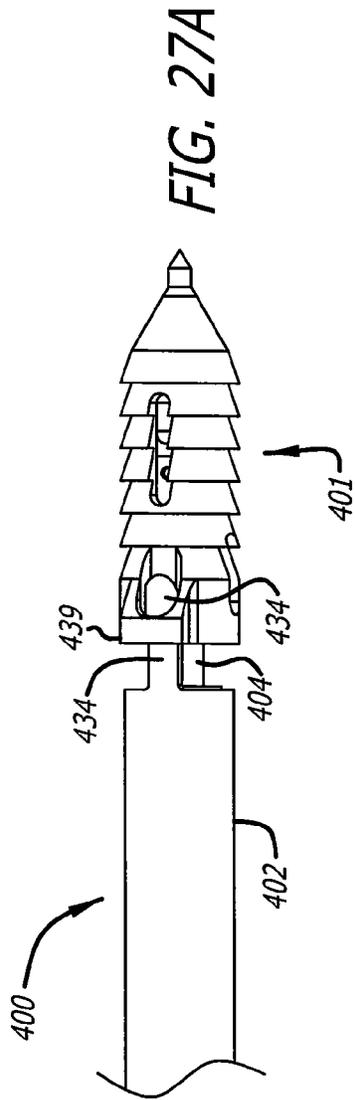
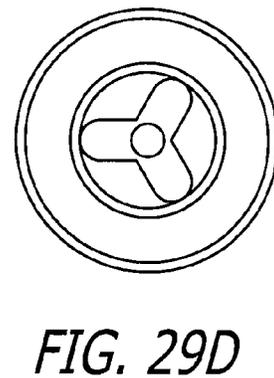
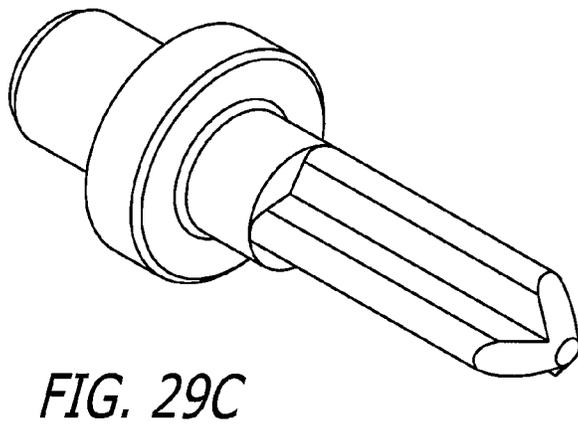
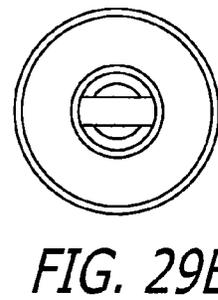
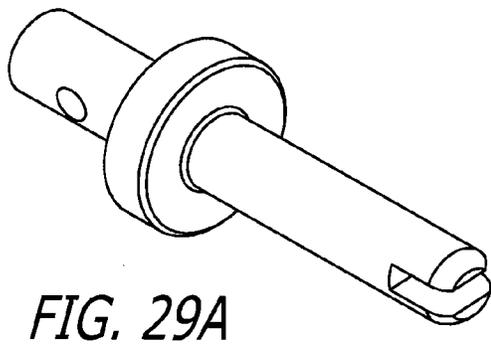
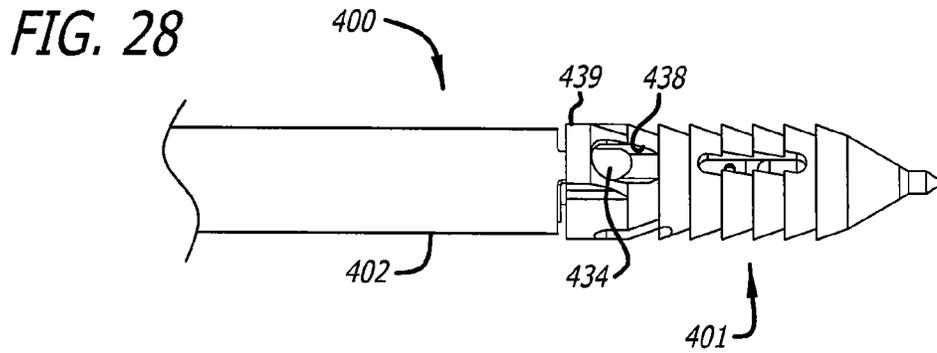


FIG. 26B





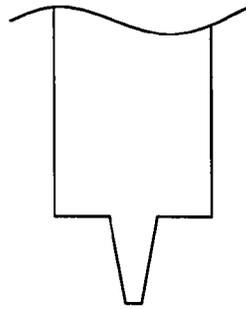


FIG. 29E

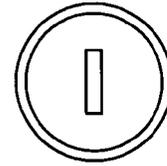


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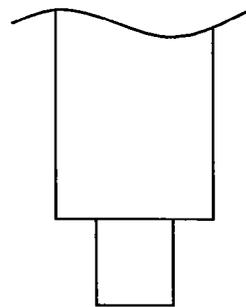


FIG. 29G

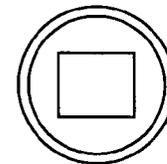


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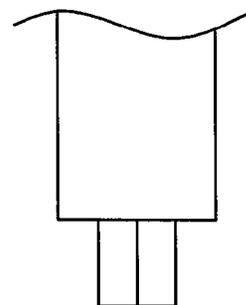


FIG. 29I

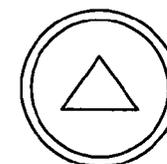


FIG. 29J

FIG. 29K

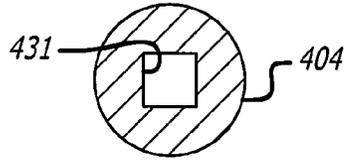
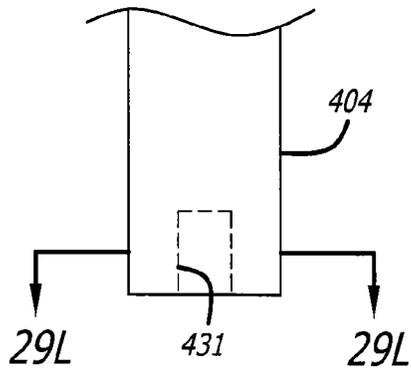


FIG. 29L

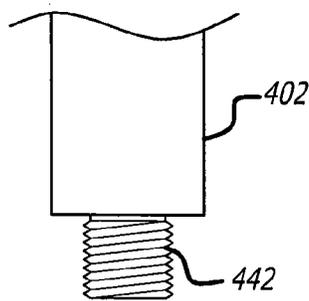


FIG. 30A

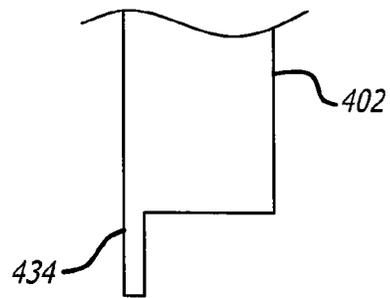


FIG. 30B

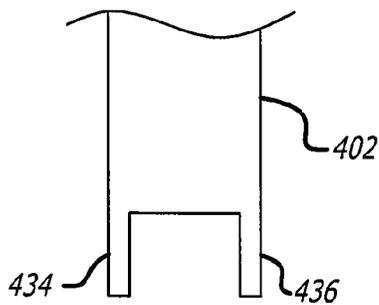


FIG. 30C

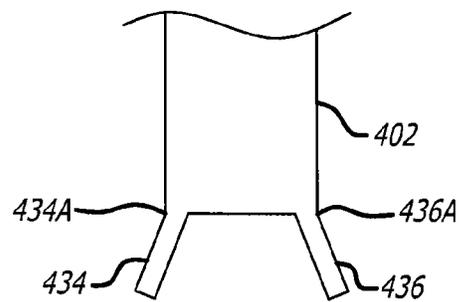


FIG. 30D

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INSERTION TOOL FOR KNOTLESS SUTURE ANCHOR FOR SOFT TISSUE REPAIR AND METHOD OF USE

FIELD OF THE INVENTION

The present invention relates to medical devices and procedures, and more particularly, to methods and devices for approximation of soft tissue to a rigid material such as bone.

BACKGROUND OF THE INVENTION

There are many medical procedures where a surgeon needs to attach soft tissue to bone. The soft tissue can be tendon or other connective tissue. One very common example of this is rotator cuff repair where a portion or all of the rotator cuff is torn or detached from the humerus. When the rotator cuff tears from the humerus, the result is pain and loss of function. Rotator cuff disease affects a large number of people worldwide, affecting many people over the age of forty. Some studies have shown a prevalence of approximately 30% in people over the age of forty (Rockwood C., et al., *The Shoulder*, Saunders, 2004; 820-821). It is estimated that as many as 17 million people in the United States may be at risk for pain and dysfunction as a result of rotator cuff injuries. While the majority of people are asymptomatic, a significant subset goes on to have disability. One study in patients with rotator cuff tears in one shoulder found that 50% of these patients who had an asymptomatic rotator cuff tear in the other shoulder went on to become symptomatic (Yamaguchi, K., et al., *J. Shoulder Elbow Surg.*, 2001; 10:199-203).

The prevalence of symptomatic rotator cuff disease is reflected in the large numbers of surgical repair for this condition. Rotator cuff repair is one of the most common orthopedic procedures performed. When a patient presents with a significant rotator cuff tear, surgical repair is performed. The goal of surgical repair of the rotator cuff is to secure the tendon to the bone in a stable manner so that the tendon can reattach to the bone and can heal. If the tendon is not stable and oscillation or micro-motion between the tendon and bone develops, the healing process will be interrupted. In this situation, it is less likely that the tendon will heal properly to the bone, resulting in a re-tear. Thus, the more stable the repair, the more successfully the tendon will heal to the bone.

Rotator cuff repair is performed open or arthroscopically, most often using suture anchors. These have one point of fixation with either one suture or several sutures attached for reattaching the tendon to the bone. While arthroscopic repair is less painful and thus more attractive to patients, many surgeons continue to perform open rotator cuff repairs. Much of the reason for this is due to the challenge of arthroscopic shoulder surgery. There is a significant learning curve in gaining the skills to be able to manage multiple strands of suture in a relatively small field of view, passing these through the tendon and knotting the sutures in the process of tying the tendon into apposition with the bone. Many of these techniques can be relatively time-consuming when compared with open surgery.

There is a growing body of literature showing that surgical rotator cuff repair has a high rate of failure. Failure of rotator cuff repairs is a well-described complication of rotator cuff repairs, both open and arthroscopic. For example, Gerber et al. found a re-tear rate of 20% following isolated repair of the supraspinatus. Bishop found a re-tear

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rate of 31% in arthroscopic and 47% in patients undergoing open repair (Bishop J., et al. *Cuff integrity after arthroscopic versus open rotator cuff repair. A prospective study*, *J. Shoulder Elbow Surg.*, 2006; 15:290-299). Galatz found an even higher re-tear rate in larger tears (Galatz, L., et al., *The outcome and repair integrity of completely arthroscopically repaired large and massive rotator cuff tears*, *J. Bone Joint Surg. Am.*, 2004; 86A:219-24). Tendon-to-bone reattachment in a rotator cuff repair procedure can fail by a number of means. In a review of failed rotator cuff surgeries evaluated at re-operation, Cummins cited as one of the weak links in the repair, the suture-tendon interface (Cummins, C. A., et al., *Mode of failure for rotator cuff repair with suture anchors identified at revision surgery*, *J. Shoulder Elbow Surg.*, 2003 March-April; 12(2):128-33). To reduce the load on any one suture, (i.e., greater distribution of loads) suture anchors used in tendon repair have begun to add multiple sutures to each suture anchor. Burkhart illustrates that the load on each suture diminishes as the number of sutures holding the tendon in place increases (Burkhart, S. S., et al., *A stepwise approach to arthroscopic rotator cuff repair based on biomechanical principles*, *Arthroscopy*, 2000 January-February; 16(1):82-90). Kim demonstrated less strain and greater tendon-bone stability in repairs made with multi row (4 fixation points) than with single row (2 fixation points). However, even in the repairs made with 4 fixation points, slippage (oscillation and micro-motion) between the tendon and bone was greater than 3.0 mm after just 200 cycles of physiological loading (Kim, D., et al., *Biomechanical comparison of a single-row versus double row suture anchor technique for rotator cuff repair*, *Am. J. Sports Med.*, 2006; 34; 407).

FIG. 1 illustrates a common prior art configuration for attaching tendon to bone. A suture anchor **102** with a pre-attached suture **105** is first driven into the cortical shell **100** and then the cancellous portion **101** of the bone **110**, after which one or both of the ends of the suture line **105** are threaded through the tendon **103**. The two ends of the suture line **105** are then connected with any one of a variety of knot types **111** to bring the tendon **103** in direct contact, or apposition, with the bone **110**. In tendon repair, it is a common practice to mechanically abrade or shave the cortical shell **100** to achieve a bleeding surface. It is believed that a bleeding surface will promote more rapid healing of the tendon to the bone. Stable apposition between the tendon and bone will promote healing while micro-motion or oscillation between the tendon and the bone may disrupt the healing of the tendon to the bone. In current tendon repair techniques, stability between the tendon and the bone largely comes from the compression the suture can apply between the tendon and bone.

The objective with tendon repair is for the connection between the tendon **103** and bone **110** to remain stable when physiological lateral force **F 108** is applied. FIG. 2 depicts how a position gap **104** may form when physiological lateral force **F 108** is applied to the tendon **103** when only sutures are used to apply downward compressive force to secure the tendon to the bone. As the force **F 108** exceeds the frictional forces between the tendon and bone and that applied by the suture, the tendon slips along the interface between the tendon and the bone and causes the flexible, non-rigid suture **105** to further compress the tendon and rotate in the direction of the applied force **F** until a new force equilibrium is achieved. Thus, the undesired oscillation that results in position gap **104** is formed. Such a gap interferes with the healing of the tendon to the bone and may compromise the repair process to an extent that it becomes unsuccessful.

Such force **F 108** may be applied by the patient using his or her humerus before full reattachment and healing of the tendon **103** to the bone **110** has occurred.

In facilitating or augmenting tendon to bone fixation in surgical rotator cuff repair, typically sutures are passed through the torn tendon a distance medially to the tear that will be sufficient to provide enough tendon to cover the greater tuberosity of the humeral bone. Tension is then applied to the sutures to pull the tendon laterally over the area of the greater tuberosity, and mattress style knots are tied in the sutures gripping the tendon to appose the tendon to the humeral bone. The ends of the sutures are then stretched laterally over the tendon, stabilizing it to the greater tuberosity, and with a knotless anchor, fixed and tensioned to the bone at a position lateral to the tear. As force **F** is applied to the tendon, the lateral fixation points will stabilize the mattress knots resulting in less gap as shown in FIG. 2. However, due to limitations in their design, current knotless anchors used for lateral fixation do not always adequately fix and tension the suture to the bone or are overly complicated to use, resulting in the potential for inadequate lateral fixation, possibly resulting in the formation of the gap shown in FIG. 2. One problem with prior art knotless suture anchors is that the insertion tool used to fix the anchor into bone and to create tension on the sutures, are inadequate and too complex to securely implant the anchor and tension the suture.

Thus what is needed is an insertion tool that will reliably and simply secure a knotless suture anchor into bone and tension a suture thread to stabilize the tendon to bone interface, which in turn will minimize gap formation and tendon/bone micro-motion and provide a greater opportunity for the tendon to reattach to the bone to heal properly.

SUMMARY OF THE INVENTION

The present invention addresses the difficulty with adequately stabilizing the apposition of soft tissue to bone in soft tissue repair. An insertion tool is provided to secure a knotless suture anchor in bone and to adjustably apply tension to a suture engaged with soft tissue to result in better suture control. The insertion tool and anchor are especially effective in a rotator cuff repair, but are not so limited.

The present invention insertion tool is configured for use with a knotless suture anchor. As disclosed herein, there are numerous embodiments of knotless suture anchors that have common structural features that are configured for use with the disclosed insertion tool of the invention. For example, all of the disclosed knotless suture anchors for implanting in bone comprise an outer tubular member having a distal end, a proximal end, and an outer wall, the outer wall having an outer dimension selected so that the outer tubular member will be retained within the bone, the outer tubular member having an inner wall, an inner tubular member is rotatably disposed within the outer tubular member, the inner tubular member having an outer diameter, and the inner tubular member and the outer tubular member each having an aperture for receiving a suture thread, wherein the outer diameter of the inner tubular member is selected to be large enough such that as the inner tubular member having a suture thread received by its aperture is rotated, the suture thread is drawn through the aperture of the outer tubular member and wraps onto the inner tubular member thereby increasing the effective diameter of the inner tubular member with the wrapped suture thread coming into contact with the inner wall of the outer tubular member, such contact

exerting an inward force on the wrapped suture thread to maintain it in position on the inner tubular member.

In keeping with the invention, the insertion tool has an elongated inner shaft rotatably positioned in an elongated outer shaft. The inner shaft can move axially relative to the outer shaft, and in another embodiment, the inner shaft is fixed axially relative to the outer shaft. The insertion tool has a pair of handles near the proximal end of the tool, and an anchor engaging member at the distal end of the tool. A first handle is used to rotate the inner shaft and the second handle is used to maintain the outer shaft stationary relative to the inner shaft. The inner shaft distal end includes an engaging member for engaging the inner tubular member of the anchor and, through rotation of the inner shaft, imparting rotational forces on the inner tubular member. In one embodiment, the engaging member is a notch that mates with a pin fixed in the proximal end of the inner tubular member. The notch fits over the pin and as the inner shaft is rotated, the notch engages the pin to impart rotational forces on the inner tubular member. The outer shaft of the insertion tool includes a distal end having at least one flange for matingly engaging the outer tubular member. In one embodiment, the outer shaft has one flange that matingly engages an aperture in the outer tubular member. The outer shaft does not rotate so that when the inner shaft rotates and imparts rotational force on the inner tubular member of the anchor, the rotational forces will not cause the outer tubular member of the anchor to rotate since the outer shaft is stationary and the flange on the outer shaft is hooked into the aperture on the outer tubular member. As the inner tubular member rotates, suture thread winds onto the inner tubular member and increases in diameter until the wraps of suture thread come into contact with the inner wall of the outer tubular member, which imparts rotational force on the outer tubular member. Because the outer shaft does not rotate, and because it is hooked into the outer tubular member, the outer tubular member will not rotate due to the rotational forces from wrapping suture thread on the rotating inner tubular member.

In one aspect of the invention, the outer shaft of the insertion tool has a pair of flanges that are slightly bent and biased outwardly so that the flanges can snap into engagement with apertures in the outer tubular member. A recess in the form of a ramp extends from the proximal end of the outer tubular member to the apertures so that the flanges can slide into the recess and along the ramp as the insertion tool is advanced into engagement with the anchor. As the flanges slide distally along the ramp they will snap outwardly when they enter the apertures in the outer tubular member.

In one embodiment, the outer shaft has threads at its distal end which matingly engage threads on the inner wall of the outer tubular member. When the outer shaft is screwed into the outer tubular member, it will prevent the outer tubular member from rotating when suture thread is wrapped onto the rotating inner tubular member of the anchor.

In another embodiment, the distal end of the inner shaft of the insertion tool has a screwdriver-like configuration that includes alternative shapes such as a flat blade, phillips or hex shape, an "x" shape, and the like. The proximal end of the inner tubular member has a corresponding recess for accepting the screwdriver-like shape on the distal end of the inner tubular member, i.e., a three-lobed or phillips- or hex-shaped recess for receiving a three-lobed or phillips- or hex-shaped protrusion on the distal end of the inner shaft. As the inner shaft is rotated, the three-lobed, phillips or hex head protrusions matingly engage the three-lobed, phillips

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or hex head recess in the inner tubular member and translate the rotational force to the inner tubular member.

The features and advantages of the invention will be more readily understood from the following detailed description which should be read in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 depicts a prior-art technique in which a suture is placed around or through a tendon that is to be held in apposition with a humeral bone in this embodiment, the suture being located through an anchor that has been impacted or screwed in the bone and is knotted above the tendon thus resulting in a compliant configuration, the figure also showing a lateral force F that may be applied to the tendon, possibly due to patient activities;

FIG. 2 demonstrates the formation of a gap in the position of the tendon in relation to the position of the tendon in FIG. 1; the movement of the tendon in forming this gap negatively affecting the reattachment and healing of the tendon with the bone, the gap formation being caused by the application of a level of the lateral force F to the tendon that overcomes the suture downward force causing the tendon to move from its desired healing position, as shown in FIG. 1;

FIG. 3 shows an assembled knotless suture anchor in accordance with aspects of the invention showing the suture traversing the anchor, the anchor having a pointed tip for facilitating impaction of the anchor in the bone, an aperture for receiving the suture or sutures, and a ratcheting mechanism located at the proximal end of the anchor in this embodiment for allowing rotation of an inner member in a first direction in relation to an outer tubular member while preventing counter-rotational movement of the inner member in a second, in this case opposite, direction in relation to an outer tubular member, the ratcheting mechanism having a pawl comprising the two ends of a pin mounted in the inner member, and the teeth of the ratchet being formed as part of the proximal edge of the outer tubular member.

FIG. 4 is a view of the assembled knotless suture anchor in which the outer tubular member has a deformable portion and a non-deformable portion showing the anchor expanded outwardly as a result of the inner member being rotated enough so that the suture has placed pressure on the deformable portion of the outer wall of the outer tubular member to cause it to protrude outwardly which increases the force of the anchor against the bone in which it is impacted thereby increasing the likelihood that the anchor will remain in place in the bone;

FIG. 5A shows a side view of an inner member usable in FIGS. 3 and 4 in which the member includes the pointed tip for impaction into the bone; the pawl of the ratchet mechanism formed by a pin at its proximal end, the ends of which extend outwardly to engage ratchet teeth formed in the outer tubular member, an aperture for receiving suture ends, and a reduced diameter section used for wrapping a certain length of suture before expanding the outer wall surface of the outer tubular member as shown in FIG. 4;

FIG. 5B is a top or proximal end-on view of the inner member of FIG. 5A showing the ratchet pawl formed by the ends of a pin in this case, the pawl doubling as a rotation control device in this embodiment to which a rotation tool may be engaged and when rotated, the pin will cause rotation of the inner member;

FIG. 5C is a schematic partially perspective view of the inner member with suture thread wrapped onto a portion of the inner member due to rotation of the inner member, the

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wrapped suture forming an enlarged outer diameter D and coming into contact with the inner wall of the outer tubular member which exerts force against the wrapped suture tending to maintain it in position on the inner member;

FIG. 5D presents another embodiment of the inner member in which a ratchet pawl is formed of an outwardly bent portion of the wall surface of the inner member for engaging teeth formed on the inner surface of the outer tubular member or apertures formed in the outer tubular member that function as teeth of a ratchet, the pin at the proximal end of the inner member functioning as a rotation control device for accepting a rotation tool that may be used to rotate the inner member as needed to adequately tighten a suture or sutures engaged with the inner tubular member, FIG. 5D showing the inner member as being tubular in configuration, at least in part;

FIG. 5E shows the inner member of 5D with surface texture for increased friction with the outer tubular member and suture engaging teeth formed and positioned to engage the wrapped suture to tend to hold it in position on the inner member so that the suture will not slip out of position due to external forces applied to it;

FIG. 5F shows a schematic diagram of another ratchet mechanism which is longitudinal in orientation with a plurality of pawls formed on the outer surface of the inner member to mesh with a plurality of teeth formed on the inner surface of the outer tubular member;

FIG. 6A shows an embodiment of the outer surface of an outer tubular member in which various portions are bent outwardly and are used to engage the walls of a bone to retain the anchor in the bone against force tending to pull it out;

FIG. 6B shows a configuration of the outer tubular member with raised ridges in longitudinal orientation to prevent rotation of the outer tubular member in bone;

FIG. 7 provides an alternate embodiment of the outer tubular member in which it is formed in the shape of a plurality of concentric frusto-conical elements having lengthwise slits permitting outward deformation or hinging in response to force applied to them from the inner wrapping of suture on the inner member;

FIG. 8 presents the knotless suture anchor of FIG. 7 showing its engagement with two ends of a suture that has been threaded through a tendon for the purpose of drawing the tendon into a particular position between the anchor and the tendon;

FIG. 9 is another embodiment of a knotless suture anchor in accordance with aspects of the present invention in which the body of the outer tubular member includes multiple longitudinal or axial direction slits that permit the slitted portion of the body to expand outwardly into contact with the bone hole to apply force to the wall of the bone hole to hold the anchor in place;

FIG. 10 is a view of the knotless suture anchor of FIGS. 7 and 8 in position in the humeral bone and being engaged with a suture that is threaded through a rotator cuff tendon to draw the tendon into desired apposition with the humeral bone and hold it in position on the humeral bone for reattachment, the anchor thus simplifying the attachment of suture to bone by eliminating the need for knots, and allowing for adjustability of the tension in the suture with a simple rotation of the inner shaft;

FIG. 11A is a schematic view showing the inner rotatable shaft with a suture thread located through it;

FIG. 11B is an axial view of the inner member being assembled with the outer tubular member with a suture end received by the aperture of the inner member and the inner

member then rotated by 180° resulting in a tortuous path of the suture creating greater friction between the suture and the inner member to lessen the possibility of slippage of the suture in the inner rotating member, the inner member having a solid portion in this embodiment which may be located as shown in the reduced-diameter length of FIG. 5A;

FIG. 11C is a view of another embodiment of an inner member in which protruding teeth are formed to further engage the threaded suture to provide even more force against it to maintain it in position in the outer tubular member, the clearance between the teeth and the outer tubular member having been reduced to further provide force against the suture to maintain it in position;

FIG. 12A shows the knotless suture anchor of FIGS. 7 and 8 with the addition of an eyelet used for guiding the suture along the outer surface of the outer tubular member to control contact of the suture with the bone, the eyelet located at the proximal end of the anchor above the bone in this embodiment

FIG. 12B presents another embodiment having two eyelets, both of which are located at the proximal end of the outer tubular member and do not extend beyond that proximal end, an internal ratchet mechanism in which apertures in the outer tubular member function as teeth and a pawl or pawls are formed on the rotatable inner member to engage the ratchet apertures, and also showing suture thread channels formed longitudinally in the outer surface of the outer tubular member in which suture thread may be positioned;

FIG. 12C presents a view of an anchor mounted in bone, the anchor having an eyelet with a suture tension indicator, which in this view is oriented longitudinally thereby indicating minimum tension on the suture;

FIG. 12D shows the tension indicator of FIG. 12C but in this case, bent into a radially outward configuration due to contact with the suture under tension, thereby indicating that the suture is at the maximum safe level of tension, in this embodiment;

FIG. 13 is a view of a system comprising two or more anchors with a suture platform functioning with sutures to create a suture bridge that increases the surface area of the suture force against the tendon to force it downward into greater contact with the bone, the suture bridge in this embodiment having the suture platform that has a surface area that exceeds that of a suture and which may be straight or curved depending on the application in which it is to be used, and further comprising in this embodiment angled spikes to engage the tendon and provide greater control over it to oppose any lateral force F that may be applied to the tendon that would tend to move the tendon and create a position gap as demonstrated in FIG. 2;

FIGS. 14 through 16 present different embodiments of a suture platform for applying pressure to a tendon;

FIG. 17 provides an alternate embodiment of a ratchet mechanism in axial or longitudinal orientation in which cantilever elements of the inner tubular member mesh with teeth on the inner surface of the outer tubular member;

FIG. 18A provides yet another alternate embodiment of a ratchet mechanism in which a plurality of pawls formed on a cap of the inner member engage teeth of the outer tubular member;

FIG. 18B provides a view of a flexible cap used as part of the ratchet mechanism, the cap having relieved portions thereby increasing its flexibility to obviate the need for a separate spring, the cap providing a spring function as well as a ratchet function;

FIG. 19 shows the formation of a pawl on the inner member, the pawl having a ramp portion that may be used

to dis-engage the pawl with the teeth of a ratchet mechanism to facilitate temporary disengagement and re-engagement of the ratchet mechanism;

FIG. 20 shows a view of the use of the pawl of FIG. 19 with the inner member and outer tubular member, in this case the inner member being axially withdrawn from the aperture tooth of the outer member so that the ratchet mechanism is non-functional and the inner member can be rotated in either rotational direction to loosen the tension on a suture if necessary;

FIG. 21 provides a view of a ratchet disengagement tool for use with the configuration of FIG. 20 whereby the inner member need not be axially moved to render the ratchet mechanism non-functional;

FIG. 22 provides a further embodiment of a knotless anchor in accordance with aspects of the invention in which a pin through the inner member is used as a rotation device; and

FIG. 23 is a side view of FIG. 22 showing further detail of the pawl formed on the inner member.

FIG. 24 is a side view of the insertion tool showing the two handles at the proximal end and the knotless suture anchor engaging members at the distal end.

FIG. 25 depicts an enlarged partial view of the proximal end of the insertion tool showing the outer shaft and outer shaft handle, and the inner shaft and inner shaft handle.

FIG. 26A depicts a partial side view of the distal end of the insertion tool of FIG. 24 showing a notch at the distal end of the inner shaft and flange at the distal end of the outer shaft.

FIG. 26B is an enlarged partial view of the distal end of the insertion tool as it is being inserted into a knotless suture anchor, the insertion tool distal end having a notch for engaging the knotless suture anchor and a flange for insertion into an aperture in the anchor.

FIG. 27A is an enlarged partial side view of the insertion tool as it is being inserted into a knotless suture anchor and further showing the distal end of the inner shaft being inserted into the anchor.

FIG. 27B is an enlarged partial view of the distal end of the insertion tool depicting the distal end of the insertion tool inserted into the knotless suture anchor with the flange on the distal end of the outer shaft engaging the aperture in the suture anchor.

FIG. 28 is an enlarged partial side view of the distal end of the insertion tool fully inserted into the knotless suture anchor and further showing the flange on the distal end of the outer shaft extending into the aperture on the anchor.

FIG. 29A is a partial view of the distal end of the insertion tool showing a notch-shaped engaging member.

FIG. 29B is an end view of the notch-shaped engaging member of FIG. 29A.

FIG. 29C is an enlarged partial view of the distal end of the insertion tool showing a hex- or phillips-type engaging member.

FIG. 29D is an end view of the hex- or phillips-shaped engaging member of FIG. 29C.

FIG. 29E is a partial view of the distal end of the insertion tool showing a blade-shaped engaging member.

FIG. 29F is an end view of the blade-shaped engaging member of FIG. 29E.

FIG. 29G is an enlarged partial view of the distal end of the insertion tool showing a square- or rectangular-shaped engaging member.

FIG. 29H is an end view of the square- or rectangular-shaped member of FIG. 29G.

FIG. 29I is an enlarged partial view of the distal end of the insertion tool showing a triangular-shaped engaging member.

FIG. 29J is an end view of the triangular-shaped engaging member of FIG. 29I.

FIG. 29K is an enlarged partial view of the distal end of the insertion tool showing a square-shaped recess engaging member.

FIG. 29L is an end view of the square-shaped recess engaging member of FIG. 29K.

FIG. 30A is an enlarged partial view of the distal end of the outer shaft depicting a male threaded member.

FIG. 30B is an enlarged partial view of the distal end of the outer shaft depicting a first flange.

FIG. 30C is an enlarged partial view of the distal end of the outer shaft showing a first flange and a second flange.

FIG. 30D is an enlarged partial view of the distal end of the outer shaft showing a first flange and a second flange, each having a bend so that the flanges are spring-biased radially outward.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

FIGS. 24-30D relate to the insertion tool of the present invention, however, the tool can be used with numerous embodiments of a knotless suture anchor which are disclosed and described in FIGS. 3-23. Thus, a description of the various anchors in FIGS. 3-23 precedes the description of the insertion tool of the invention.

Referring now in more detail to the exemplary drawings for purposes of illustrating embodiments, wherein like reference numerals designate corresponding or like elements among the several views, FIG. 3 shows an assembled knotless suture anchor 120 in accordance with aspects of the invention. The anchor has received an unknotted suture thread 122 and the untied ends 124 and 126 of the thread are shown at the left of the anchor. The anchor has a pointed tip 128 for facilitating penetration of the anchor into the bone with impaction, an aperture 130 for receiving the suture, and a ratcheting mechanism 132 located at the proximal end 138 of the anchor, in this embodiment, for allowing rotation of an inner member 134 in a first direction in relation to an outer tubular member 136 while preventing rotational movement of the inner member in a second, in this case opposite, direction in relation to an outer tubular member.

In FIG. 4, the anchor 120 of FIG. 3 is shown in an expanded configuration. The outer tubular member 136, also referred to herein as a shell, has a deformable portion 140 and a non-deformable portion 142, although in this case, there are two non-deformable portions. The deformable portion of the outer tubular member is shown expanded outwardly as a result of the inner member 134 being rotated enough so that the suture 122 threaded in the anchor 120 has placed outward pressure on the deformable portion of the outer wall 144 of the outer tubular member to cause it to protrude 146 outwardly which increases the force of the anchor against a hole in the bone in which it is impacted thereby increasing the likelihood that the anchor will remain in place in the bone. In this case, the outer tubular member has a plurality of longitudinal or lengthwise slits 156 spaced closely enough together to form a plurality of strips 158 of the outer surface of the outer tubular member that bow outwardly when pressure is applied to them internally by the inner member 134 and wrapped suture thread, as will be shown and described below. These strips may be considered to be buckling elements since they bow or buckle in

response to radial force from the inner member. The short cantilevered elements 135 that also protrude outward may be considered to be barbs that may increase friction with and may pierce the bone to prevent movement of the anchor out of the bone.

FIGS. 3 and 4 also show a portion of the ratchet mechanism 132 used in this embodiment. A pin 148 having protruding ends (shown in more detail in later figures) engages teeth 150 that are formed in the proximal edge of the outer tubular member 136. This permits rotation of the inner member 134 in relation to the outer tubular member in a first direction but prevents counter-rotation (rotation in the opposite direction). The distal end 152 of the outer tubular member includes a spring 154, in this case a leaf spring, that is engaged in contact with both the inner member and the outer tubular member to bias the outer tubular member towards the pin 148 of the ratchet mechanism.

FIGS. 5A and 5B show a side view and top view respectively of an inner member 134, which is tubular in this case, also referred to as a rotatable shaft. This inner member is usable in FIGS. 3 and 4 and includes the pointed tip 128 for impaction into the bone at its distal end. At the proximal end 168, the inner member includes the pawl 148 of the ratchet mechanism formed by a pin 148 mounted in a diametrical orientation to the inner member and outer tubular member, the ends 160 and 162 of the pin extending outwardly to engage ratchet teeth formed in the outer tubular member as shown in FIGS. 3 and 4. The inner member has an aperture 164 for receiving the two ends 124 and 126 of the suture 122, and a reduced diameter section 166 used for wrapping the suture onto the inner member. It will be noted that the pin 148 extends across the proximal end 168 of the inner member which is hollow. This configuration enables use of an insertion tool to engage the pin. In the case of an insertion tool engaged with the pin, rotation of the pin will cause rotation of the inner member (see FIGS. 24-30D).

Although FIG. 5B shows the inner member as being hollow through to the pointed tip 128, this need not be the case. In other embodiments the inner tubular member may be partially solid or completely solid. The designations "tubular" or "shaft" are used for convenience of reference only.

Turning now to FIG. 5C, the inner member 134 mounted within the outer tubular member 136 is shown in a schematic view with certain details removed for clarity of illustration. The suture thread has been wrapped 123 onto the inner member thereby forming an increased diameter D of material on the inner member. The suture is not tied or knotted and need not be knotted. The suture ends 124 and 126 are loose, however, the anchor with the configuration shown, fully captures the suture thread and provides a firm anchor of it to bone. There is no need to tie the ends of the suture thread into a knot. The diameter of suture over the inner member has increased the effective diameter of the inner member to a size where the suture has contacted the deformable portion of the outer tubular member. This contact causes the outer tubular member to apply force or pressure to the contacting suture thread which causes the suture thread to maintain its position on the inner member and to not slip or pull out of the inner member.

FIGS. 5D, 5E, and 5F present an alternate embodiment of a ratchet mechanism used to permit relative rotational motion between the inner member and the outer tubular member in one direction 171 (FIG. 5F—arrow with a check mark) and prevent counter-rotation 173 (FIG. 5F—arrow with an "X"). FIG. 5D shows an inner member 134 with the pointed tip of FIG. 5A excluded, in which a ratchet pawl is

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provided by means of an outwardly angled portion 172 formed from the wall of the inner tubular member. The angled portion extends outwardly far enough to engage raised teeth 174 formed on the inner surface 176 of the outer tubular member 136 as shown in the schematic view of FIG. 5F. Only one pawl 172 is shown in FIG. 5D; however, as shown in FIG. 5F, a plurality may be formed on the inner member. The raised teeth 174 on the inner surface of the outer tubular member may take forms of protrusion different from that shown in FIG. 5F. Although not shown, relief slits or other features may be formed in the outer tubular member at appropriate locations to permit its accommodation of the interference of the protrusions with the pawls 172 as they encounter each other during rotation. Also shown in FIG. 5D is the pin 148 at the proximal end of the inner member, and the aperture 164 formed in the reduced-diameter section 166.

FIG. 5E presents further detail. The outer surface of the inner member 134 includes further features, such as texturing 177 to assist in creating friction between the inner member and the suture threads or the outer member so that undesirable rotation or suture shift do not occur. Furthermore, suture teeth 178 may be formed on the inner member around the suture aperture 164 so that further pressure is applied to the suture thread to maintain its position on the inner member of the anchor so that it does not slip or pull out entirely. The effect of the suture teeth 178 will be seen more clearly by reference to FIG. 11C. Additionally, a square drive socket 179 may be used for rotation of the inner member 134, or other embodiments (as more fully discussed below) may be provided in which other shapes or types of drivers are used, such as a hex drive.

FIGS. 6A and 6B provide views of different outer surfaces 180 that may be incorporated into an outer tubular member 136 to retain the anchor both axially and rotationally in position in bone. In FIG. 6A, axial retaining devices are provided comprising various portions 182 of the outer surface 180 that are bent or are bendable outwardly for use in axially retaining the anchor in place. These axial retaining devices will engage the wall of a bone in which the anchor is impacted to retain the anchor in the bone. The protruding portions 182 in FIG. 6A include cantilevers 184 with the unattached ends 186 of the cantilevers pointing in the proximal direction 188 so that they will engage the bone to prevent its extraction if a pulling-out force is applied to the anchor. These cantilever ends may just apply frictional forces with the bone or may pierce the bone thereby generating mechanical interference with extraction. The non-cantilever portions 190 bow outwardly and are capable of applying frictional forces with the bone to resist extraction of the anchor. The outwardly bowing configuration may be caused by the expansion of the outer tubular member or some or all of the retaining members of FIG. 6A may be initially formed or pre-bent in the outwardly protruding configuration and used to engage the wall of the bone whether or not the outer tubular member is expanded.

Turning now to the top view shown in FIG. 6B, rotational retaining members 192 are formed on the outer surface 180 of the outer tubular member 136. In this case, the rotational retaining devices comprise raised ridges or teeth that extend for some longitudinal distance along the outer tubular member. During impaction, the rotational retaining devices will engage bone structure and will prevent rotation of the outer tubular member. This can be quite useful in holding the outer member stationary thereby maintaining the successful operation of the ratcheting mechanism shown, for example, in FIGS. 3 and 4. For clarity of illustration, certain drawing

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numerals, such as 174 and 192, are only shown with lead lines to one or a few of the elements described for that numeral. However, the numerals are meant to apply to all such relevant elements.

FIG. 7 is a side view of an anchor 198 and an outer tubular member 200. The body of the outer tubular member is formed in the shape of a plurality of interconnected, concentric, frusto-conical elements 202, some of which include lengthwise slits 204 that permit outward expansion of their larger-diameter ends 206 in response to outward force applied to them from the wrapping of suture on the inner member 134 (FIG. 5C). For clarity of illustration, certain drawing numerals, such as 202, 204, and 206, are only shown with lead lines to one or a few of the elements described for that numeral. However, the numerals are meant to apply to all such relevant elements.

FIG. 8 presents a knotless suture anchor 198 incorporating elements of FIG. 7 showing its engagement with two ends 124 and 126 of a suture thread 122 that has been threaded through a tendon 103. The anchor may be used to adjust the tension on the suture thread and/or may be used in drawing the tendon into a desired position between the anchor and the tendon. Due to the unique design of the anchor 198 in accordance with aspects of the invention, there is no need to knot the suture thread. The combination of a ratchet mechanism 132 and internal pressure from the outer tubular member 200 on the suture thread that has been wrapped on the inner tubular member 134, as shown and described in FIG. 5C, avoids slippage of the suture thread in the anchor. Additionally, the automatic outward expansion of the outer tubular member serves to further retain the anchor in the bone.

The suture apertures 130 in the outer tubular member 200 shown in FIGS. 7 through 10, are diametrical in orientation, and there are two of them. Having two apertures is shown as an alternative embodiment in that a single aperture may suffice.

FIG. 9 shows a knotless suture anchor 210 in which the deformable portion 140 of the outer tubular member is located between two non-deformable portions 142 and comprises longitudinal strips 158 of the outer tubular member that bow outwardly as shown to contact surrounding bone and provide axial retention of the anchor in the bone. As the suture thread wraps 123 onto the inner member 134, the wrapped suture provides outward force against the deformable section 140 of the outer tubular member causing it to bow outwardly, while at the same time, the outer tubular member in turn provides force against the wrapping suture thread tending to prevent slippage of the suture thread on the inner tubular member.

FIG. 10 is a view of the knotless suture anchor 198 of FIGS. 7 and 8 impacted in position in the humeral bone 110 and being engaged with a suture thread 122 that is threaded through a rotator cuff tendon 103 to draw the tendon into desired apposition 120 with the humeral bone and hold it in position on the humeral bone for reattachment. As shown, an anchor in accordance with aspects of the invention is knotless thereby simplifying the attachment of suture to bone by eliminating the need for knots, and allowing for adjustability of the tension in the suture with a simple rotation of the inner shaft.

FIGS. 11A through 11C are axial cross-section views of the inner member 134 being assembled with the outer tubular member 136 and the path of the suture thread 122 threaded through the aperture 164 of the inner member and the aperture 130 of the outer tubular member. In FIG. 11A, the suture comprises two threads. The aperture of the inner

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member is aligned with the aperture of the outer tubular member and the suture threads **122** are placed straight through the anchor. For clarity of illustration, FIGS. **11B** and **11C** only show a single suture thread. In FIG. **11B**, the inner member has been rotated by one hundred and eighty degrees (180°) showing how the suture thread is wrapped about the inner member **134**. This increasing wrapping will increase the force of the suture thread on the inner tubular member thereby lessening the possibility of slippage of the suture in the inner tubular member.

In FIG. **11C**, the inner member includes suture teeth **178** as shown in FIG. **5E**. These suture teeth are used to assist in maintaining the suture thread **122** in position on the inner member **134**. Also, in this embodiment, there is less clearance between the inner member and the inner wall **181** of the outer member, thus putting further pressure or force on the suture thread **122** to maintain its position on the inner member.

FIG. **12A** provides a view of the anchor **198** of FIGS. **7** and **8** impacted into bone **110** showing the addition of a suture thread guide **230** disposed at the proximal end **232** of the outer tubular member **136**. The suture thread guide comprises an eyelet, the aperture **234** of which receives a suture thread to guide the suture thread along the outer surface **236** of the outer tubular member thereby restricting contact of the suture with the surrounding bone **110**. It has been noted that if not so guided or restricted in movement, the suture thread **122** can have a sawing or "cheese cutting" effect on the bone **110** when forces are imparted to it that cause the suture to move, thereby undesirably removing some of the bone. Such sawing or bone cutting can undesirably loosen the tension on the suture since the path of the suture will have now been shortened.

Another advantage to the eyelet is that it redirects the force that the suture tension applies to the anchor. When not confined by the eyelet, the suture can apply outwardly-directed force on the anchor that tends to force the anchor out of its position in the bone. When an eyelet is used however, that eyelet functions to translate the tension on the suture to lateral force on the anchor thereby greatly lessening the tendency of the suture tension to force the anchor from the bone and thereby providing a more stable anchor.

FIG. **12B** presents another anchor embodiment in which two suture thread guides **230** are provided. The apertures **234** of the guides are oriented in parallel with the longitudinal axis of the inner member **134** and are located at the proximal end **232** of the outer tubular member **136**. As shown, the suture thread guides do not extend beyond the proximal end of the outer member. Aligned with each of the thread guides **230** in this embodiment is a guide channel **224** located between the guide **230** and the aperture **130** in the outer member. Only one guide channel can be seen in FIG. **12B**. Each guide channel comprises a relieved portion of the outer surface of the outer tubular member having a depth selected so as to receive a suture thread or threads, whereby a suture thread disposed in the knotless suture anchor **218** is guided by the thread guides and guide channels to positions that are away from contact with surrounding bone **110**.

Portions of a ratcheting mechanism can also be seen in FIG. **12B**. In this case, the ratchet teeth are provided by ratchet apertures **226**, one of which can be seen. Shown as engaged with this ratchet aperture is a flexible ratchet pawl **228** that is mounted on and rotates with the inner member **134**, although internal details cannot be seen in this figure. Refer to FIG. **5D** for a possible flexible pawl that would function in the embodiment of FIG. **12B**. A plurality of

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pawls may be used on the inner member. A plurality of ratchet apertures may also be provided.

A further eyelet-connected feature is shown in FIGS. **12C** and **12D**. A tension indicator **310** is formed at the outer edge of one of the eyelets **230**, also known as a suture guide. The tension indicator is located such that it will contact a suture thread **122** received by the guide **230** and will give a visual indication of the tension on that thread **122**. In this case shown in FIG. **12C**, the indicator **310** has been formed in a longitudinal configuration parallel with the longitudinal axis of the anchor and remains in that configuration when there is no tension on an engaged suture thread. However, the indicator is meant to deform due to tension on the suture and when that tension is high, it will deform to the configuration shown in FIG. **12D**. The indicator **310** in FIG. **12D** is no longer longitudinally oriented but is instead now radially or diametrically oriented providing a highly visual indication of the much higher suture tension level. The mounting and resistance to deformation of the indicator **310** were selected such that the indicator would assume the configuration shown in FIG. **12D** only when the tension on the suture was at the highest level that the suture thread is capable of handling safely. Above that level of tension, the suture thread is in danger of breaking.

Thus the tension indicator of FIGS. **12C** and **12D** provides a highly visual indication of the level of tension. The shape of the indicator may be varied as desired however, it must come into contact with the engaged suture thread.

FIG. **13** is a view of a tendon repair system **240** comprising two or more anchors with a suture platform **242** functioning with a suture **122** or sutures to create a suture bridge **244** that increases the surface area of the suture **122** force against the tendon **103** to force the tendon downward into greater, and more uniform, apposition with the bone **110** for reattachment and healing. The suture bridge in this configuration comprises the suture platform that has a surface area that exceeds that of a suture. Two anchors are shown, one of which may be a standard passive or static anchor **246** that is impacted into the bone and that simply includes a loop for receiving a suture thread. The other anchor may be a knotless anchor **238** such as one in accordance with the present invention. A suture thread may be looped through the passive anchor, then drawn through the tendon and into the suture platform as shown, and either through or around the tendon again, and the loose ends of the suture thread received by the knotless anchor **238**. The inner tubular member of the knotless anchor is then rotated to tighten the suture thread onto the suture bridge thereby pressing the tendon into better contact with the bone.

The suture platform **242** may have spikes **248** as shown in FIG. **13** that enter the tendon to provide better control over the position of the tendon and to keep it in the desired fixed position in apposition with the bone. When the spikes are angled as shown in FIG. **13**, in a direction against the expected force to which the tendon would be subjected, the tendon is less likely to move and create gaps as shown in FIG. **2**. The spikes should be short enough so that they do not completely traverse the tendon and make contact with the bone. That is, the length of the spikes should be shorter than the width of the tendon with which they are engaged.

The suture platform **242** may be straight or curved or have other shapes depending on the application in which it is to be used. For example, the platform may have the shapes **250**, **252**, or **254** as shown in FIGS. **14**, **15**, and **16** respectively, depending on the tendon to be healed and the bone to which it is attached or to which it is to be reattached. All platforms may have apertures **256** and/or may have specially designed

lateral suture guides **258** such as those shown in FIG. **15**. The shapes and configurations shown in the figures are exemplary only.

Other ratcheting mechanisms may be used, two examples of which are shown in FIGS. **17**, **18A**, and **18B**, although other mechanisms may function effectively. In FIG. **17**, the inner member **260** has been formed with a plurality of axially-extending ratchet pawls **262**. These are cantilever in nature and are flexible enough to bend inwardly as they follow the ramp **264** of the teeth **266** formed on the inside surface of the outer tubular member **136**. The pawls then snap back outwardly into their normal position after passing the ramp **264** of a tooth **266** and encountering the stop surface **268** of the teeth. They will then prevent counter-rotation of the inner tubular member **260**.

In FIG. **18A**, the inner member **270** has a cap **272** having teeth **274** formed at its distal end **276**. The outer tubular member **278** has teeth **280** formed at its distal end **282**. The teeth on the inner tubular member and those on the outer tubular member are complementary and when the inner tubular member is slid into position within the outer tubular member, the meshing teeth will act as a ratchet mechanism. A spring, such as the leaf spring **154** shown in FIG. **4**, is used to maintain the ratchet mechanism functioning. In the case where the outward bowing of the deformable portion **140** (FIG. **9**) shortens the length of the outer tubular member, the spring **154** nevertheless will force the teeth of the outer tubular member into continued engagement with the pawl or pawls of the inner tubular member. Such an approach may not be needed when the ratchet mechanism is formed longitudinally such as in FIG. **5D**.

FIG. **18B** presents a top perspective view of the cap **272** of FIG. **18A**. Shown on the top surface is the drive socket **179** of FIG. **5E**, as well as relieved portions **312** functioning to increase the flexibility of the outer perimeter of the cap. The size and locations of the relieved areas **312** are selected to result in a desired amount of spring in the cap such that it will function as a ratchet device wherein the perimeter rides up the ramps of the teeth **280** on the outer tubular member **278** yet will spring back into engagement with each stop surface of the ratchet at the ramp's end. Such spring function will obviate the need for a separate spring to hold the ratchet teeth and pawl together.

As used herein, "apposition" is meant to mean in contact with as well as have other meanings commonly associated with it. For example, when the tendon is in "apposition" with the bone, one meaning is that the tendon is in contact with the bone.

Depending on the particular ratchet mechanism, the inner member may be moved an axially controlled amount to disengage its pawl or pawls from the teeth of the outer tubular member such that the ratchet mechanism is temporarily disengaged. This disengagement will permit counter-rotation of the inner member in relation to the outer tubular member to loosen the suture threaded through it. In such a configuration, the spring is disposed so that it can be overcome to disengage the ratchet mechanism, yet has enough length to force the ratchet mechanism back into engagement once the separating force is removed.

Such a mechanism is shown in FIGS. **19** and **20**. In FIG. **19**, the inner member **290** is cut **292** as shown to create a longitudinal pawl **294** having a ramp **296** and a straight portion **298** for engaging teeth formed on the inside of the outer tubular member (see for example FIG. **5F**). The pawl of FIG. **19** will look similar to that of FIG. **5D** numeral **172** except that the pawl of FIG. **19** will have the ramp **296** at the distal or proximal end of the pawl. As shown in FIG. **20**, the

inner member **290** has been pulled axially in relation to the outer tubular member **300** so that the pawl **294** disengages from the teeth **302** (in this case a ratchet aperture functioning as a tooth) and the suture can then be loosened from the anchor as desired by rotating the inner member in a counter-rotation direction, or the rotation direction prevented by an engaged ratchet mechanism. The ramped edge **296** of the pawl facilitates this disengagement of the ratchet mechanism in that it more easily permits the pawl **294** to be separated from the aperture **302**. Also, there may be an internal spring (not shown) that biases the inner member into the outer member so that the ratchet mechanism is engaged. This spring force would need to be overcome to disengage the ratchet as described above.

The inner member may then be slid back into the outer member to re-engage the ratchet mechanism for normal operation. In the case shown in FIG. **20**, the inner member is shown as having been axially moved much farther than it would normally be moved for disengagement. This is shown solely for purposes of clarity in illustration. Normally, the inner member would be axially moved only far enough for the pawl **298** to disengage the ratchet aperture **302**, or just out of the "tooth."

One of those other possible implementations is shown in FIG. **21**, in which a disengagement shaft **314** is used to slide between the outer tubular member **300** and the inner member (not shown) to move the pawl **294** inward away from the apertures **302** so that the inner member may be rotated in either direction. When in this configuration, the tension on the suture can be lessened. The disengagement shaft may be axially shifted between functional (disengaging the ratchet mechanism) and non-functional (not affecting the ratchet mechanism) positions.

Referring now to FIGS. **22** and **23**, there is shown an anchor **320** in which an inner rotatable member **134** has a diametrical pin **148** mounted at its proximal end **232** that may be used to receive an insertion tool (as further described below). This design has similarities to that of FIG. **12B** except that no suture channels are formed in the outer surface of the outer tubular member. The internal ratcheting mechanism is provided however as well as two eyelets or suture guide devices **230** located opposite each other. As in FIG. **12B**, the ratchet mechanism uses aperture teeth **226** and a pawl **228** is mounted to the inner member.

Anchor **120** could be made from a non-bioresorbable or non-biodegradable material such as titanium, stainless steel, nickel-titanium alloy (nitinol), PEEK or other suitable material commonly used in orthopedic implants. Polymers synthesized from monomers comprising esters, anhydrides, orthoesters, and amides are particularly suitable for biodegradation useful for an alternative embodiment anchor **120** that is bioresorbable or biodegradable. Examples of biodegradable polymers are polyglycolide, polylactide, poly- α -caprolactone, polydiacxonone, polyglyconate, polylactide-coglycolide, and block and random copolymers of these polymers.

It may be desired to reduce the likelihood of the development of fibrotic tissue around the directional anchors or angled spikes **248** (FIG. **13**) which may increase stiffness in the tendon. Certain drugs such as steroids, have been found to inhibit cell growth leading to scar tissue or fibrotic tissue growth. Examples of therapeutic drugs or pharmacologic compounds that may be loaded onto the directional anchors (angled spikes) or into a polymeric coating on the anchors or infused into the area surrounding the anchors include steroids, taxol, aspirin, prostaglandins, and the like. Various therapeutic agents such as antithrombogenic or antiprolif-

erative drugs are used to further control scar tissue formation. Examples of therapeutic agents or drugs that are suitable for use in accordance with the present invention include 17-beta estradiol, sirolimus, everolimus, actinomycin D (ActD), taxol, paclitaxel, or derivatives and analogs thereof. Examples of agents include other antiproliferative substances as well as antineoplastic, anti-inflammatory, antiplatelet, anticoagulant, antifibrin, antithrombin, antimetabolic, antibiotic, and antioxidant substances. Examples of antineoplastics include taxol (paclitaxel and docetaxel). Further examples of therapeutic drugs or agents include antiplatelets, anticoagulants, antifibrins, anti-inflammatories, antithrombins, and antiproliferatives. Examples of antiplatelets, anticoagulants, antifibrins, and antithrombins include, but are not limited to, sodium heparin, low molecular weight heparin, hirudin, argatroban, forskolin, vapiprost, prostacyclin and prostacyclin analogs, dextran, D-phe-pro-arg-chloromethylketone (synthetic antithrombin), dipyridamole, glycoprotein IIb/IIIa platelet membrane receptor antagonist, recombinant hirudin, thrombin inhibitor (available from Biogen located in Cambridge, Mass.), and 7E-3B® (an antiplatelet drug from Centocor located in Malvern, Pa.). Examples of antimetabolic agents include methotrexate, azathioprine, vincristine, vinblastine, fluorouracil, adriamycin, and mutamycin. Examples of cytostatic or antiproliferative agents include angiopentin (a somatostatin analog from Ibsen located in the United Kingdom), angiotensin converting enzyme inhibitors such as Captopril® (available from Squibb located in New York, N.Y.), Cilazapril® (available from Hoffman-LaRoche located in Basel, Switzerland), or Lisinopril® (available from Merck located in Whitehouse Station, N.J.); calcium channel blockers (such as Nifedipine), colchicine, fibroblast growth factor (FGF) antagonists, fish oil (omega 3-fatty acid), histamine antagonists, Lovastatin® (an inhibitor of HMG-CoA reductase, a cholesterol lowering drug from Merck), methotrexate, monoclonal antibodies (such as PDGF receptors), nitroprusside, phosphodiesterase inhibitors, prostaglandin inhibitor (available from GlaxoSmithKline located in United Kingdom), Seramin (a PDGF antagonist), serotonin blockers, steroids, thioprotease inhibitors, triazolopyrimidine (a PDGF antagonist), and nitric oxide. Other therapeutic drugs or agents which may be appropriate include alpha-interferon, genetically engineered epithelial cells, and dexamethasone. It may also be desirable to incorporate osteogenic or angiogenic factors, or growth factors such as TEFB or BMP-X with the directional anchors to promote bone to tendon healing.

Although the ratchet is shown with the pawl located on the inner member and the teeth located on the outer tubular member, other configurations of a ratchet may be equally usable, some of which have been shown and described. For example, a pawl may be located on the outer member with the ratchet teeth locate on the inner member. Other arrangements may be used to create a movement in one direction. Furthermore, the anchor is repeatedly shown as being positioned in the bone so that its proximal end is about level with the bone surface. However, the anchor may in fact be mounted so that its proximal end is further within the bone or further out of the bone. Additionally, the material used for the anchor may be selected in dependence on the hardness of the tissue in which the anchor is to be mounted. Harder tissue may require a titanium anchor while softer tissue may allow use of a softer plastic material for the anchor. The design of various embodiment enables an anchor in accordance with the invention to be directly impacted into bone.

In keeping with the invention, and insertion tool **400** is provided for use with any of the knotless suture anchors

disclosed herein. Referring to FIG. **24**, the elongated insertion tool **400** has an outer shaft **402** and an inner shaft **404** positioned within the outer shaft. The outer shaft has a handle **406** positioned at the proximal end **408** of the outer shaft. The inner shaft also has a handle **410** located at the proximal end **412** of the inner shaft. As will be described more fully herein, the outer shaft handle **406** and the inner shaft handle **410** are manipulated by the surgeon in order to wind the suture onto the knotless suture anchor with minimal effort.

Referring to FIGS. **24-28**, the inner shaft **404** has a distal end **414** and an anchor-engaging member **416** at the inner shaft distal end **414**. In one embodiment, a notch-shaped engaging member **418** is positioned at distal end **414** and is configured to engage a pin **148**, in the anchor **134**, as shown for example in FIG. **5B**. Alternative embodiments of the notch-shaped engaging member **418** are shown in FIGS. **29A-29L**. For example, FIGS. **29A** and **29B** show the notch-shaped engaging member **418** for receiving the pin of any of the suture anchors disclosed herein. FIGS. **29E** and **29F** shows an inner shaft **404** having a blade-shaped engaging member **420** at its distal end. Similarly, inner shaft **404** has at its distal end a tri-lobed-shaped or phillips-shaped (four lobes) engaging member **422** (FIGS. **29C** and **29D**), a square-shaped engaging member **424** or rectangular-shaped engaging member **430** (FIGS. **29G** and **29H**), or a hex-shaped engaging member **426** or triangular-shaped engaging member **428** (FIGS. **29I** and **29J**), which are similar to the embodiment shown in FIG. **29F**. Referring to FIGS. **29K** and **29L**, the inner shaft **404** has a square-shaped recess **431** that matingly can receive a protrusion (not shown) extending from a knotless suture anchor **401** for the purpose of rotating an inner tubular member **433** of the knotless suture anchor. The recess **431** can have any of a number of shapes including a square shape, rectangular shape, triangular shape, hex shape, and the like. The embodiments shown in FIGS. **29C-29J** can be used to matingly engage a recess **432** in the inner tubular member of any of the suture anchors disclosed herein. For example, in FIG. **18B**, a drive socket **179** will matingly receive a square-shaped engaging member **424** as shown in FIG. **29F** and which fits into the recess **432** shown in FIG. **18B**.

When the inner shaft **404** of the insertion tool **400** is rotated to impart a rotational force to the inner tubular member of the knotless suture anchor, the outer shaft **402** of the insertion tool is used to stabilize and prevent any inadvertent rotation of the outer tubular member of the knotless suture anchor. In other words, it is important to keep the outer tubular member of the anchor from rotating as the inner tubular member rotates and wraps suture thread around the diameter of the inner tubular member. Thus, as shown in FIGS. **30A-30D**, various embodiments of a protrusion on the distal end of the outer shaft **404** are shown which will engage with the outer tubular member. FIGS. **30B-30D**, show a first flange (or protrusion) **434** for engaging an aperture in the outer tubular member of the knotless suture anchor. While first flange **434** will adequately prevent rotation of the outer tubular member, an alternative embodiment, as shown in FIG. **30C**, shows first flange **434** and second flange **436** diametrically opposed to each other, both of which engage apertures in the outer tubular member of the anchor to stabilize the anchor and prevent rotation as the inner tubular member is rotated by the inner shaft **404**. As can be seen in FIGS. **26B**, **27A**, **27B** and **28**, the knotless suture anchor **401** has an aperture **438** in the outer tubular member **439**. The first flange **434** of the outer shaft **402** is positioned in the aperture **438**, which will keep the outer

tubular member stationary since the outer shaft **402** will not rotate as the inner shaft rotates and wraps suture thread around the inner tubular member. The first flange **434** extends into the aperture **438** as shown in FIG. **28**. As shown in FIG. **30D**, it may be desirable to have a bend **434A** in first flange **434** and a second bend **436A** in second flange **436**, and have the flanges biased outwardly so that as the flanges are inserted into apertures **438**, they will essentially snap into place and provide a locking arrangement with the apertures. In order to assist the flanges **434,436,434A** and **436A** into locking engagement with the apertures **438**, a ramp **440** (not shown) can be provided above the aperture **438** on the inner wall of the outer tubular member **439** so that the flanges can slide along the ramp prior to snapping into engagement with the apertures **438**. While flanges **434,436** are disclosed, any protrusion extending from the distal end of the outer shaft **402** that are configured for temporary locking engagement with the outer tubular member **439** of anchor **402** are suitable.

As shown in FIG. **30A**, the outer shaft **402** is provided with a protrusion in the form of male threads **442** at its distal end for matingly engaging female threads on the inner wall of the outer tubular member **439**. In this embodiment, male threads **442** are screwed into mating female threads (not shown) on the inner wall of the outer tubular member **439**. After the threads are engaged, the outer shaft **402** prevents the outer tubular member **439** from rotating as the inner tubular member is rotated by the inner shaft **404** and wraps suture thread onto the inner tubular member.

With reference to any of the embodiments of the knotless suture anchor disclosed herein, the method of using the insertion tool **400** is described. As shown in FIGS. **26A-28** for example, as previously described, knotless suture anchor **401** (which is representative of any of the anchors disclosed herein) is placed into bone and prepared for use in suturing a tendon to bone. The insertion tool **400** is positioned so that the inner shaft **404** is advanced into the inner tubular member of the anchor **401**. In one embodiment, inner shaft **404** moves axially relative to the outer shaft **402** so that the distal end **414** of the inner shaft can be positioned in the inner tubular member **433** without engaging pin **148** (FIG. **5F**). The pin in anchor **401** is not visible, but is similar to pin **148** of FIG. **5F**. The outer shaft **402** is then advanced distally and rotated so that first flange **434** on the distal end of the outer shaft **402** is inserted into aperture **438** of the outer tubular member **439**. First flange **434** engages aperture **438** and prevents the outer tubular member **439** of the anchor **401** from rotating. The inner shaft is then rotated and further advanced distally so that notched-shaped member **418** engages pin **148** (FIG. **5F**). With the surgeon grasping handle **406** on the outer shaft **402** to prevent rotation, the surgeon rotates handle **410** on the inner shaft **404** in order to impart rotational force to the inner shaft, and hence to the notched-shaped member **418** and the pin **148** in the inner tubular member **433** of the anchor **401**. As the inner shaft **404** is further rotated, the suture threads, as disclosed herein, will wrap onto the inner tubular member and increase in diameter until the suture threads impart a locking force as they engage the inner wall of the outer tubular member **439** as previously described. While this rotational force resulting from the increased diameter of the suture threads wrapping onto the inner tubular member may try to rotate the outer tubular member **439**, the first flange **434** is in locking engagement with aperture **438** and prevents rotation since the outer shaft **402** will not rotate. After the proper tension has been imparted to the suture threads, the insertion tool **400** is withdrawn from the patient, and the notched-shaped

engaging member **418** easily slides away from the pin **148** in the anchor and the first flange **434** easily slides out of engagement with the aperture **438** of the outer tubular member **439**.

The methods of use of the other embodiments of insertion tool **400** are easily envisioned in view of the foregoing description of use of the tool. For example, referring to the embodiment of the anchor shown in FIG. **18B**, a recess **432** in the form of drive socket **179** is configured for receiving a square-shaped engaging member **424** as shown in FIG. **29F**. Thus, the use of the square-shaped engaging member **424**, which matingly engages drive socket **179**, is the same as that described above with respect to the notch-shaped member **418**. Likewise, the embodiments shown for the engagement of the aperture **438** by first flange **434**, could also include second flange **436** for engagement with a diametrically opposed aperture on the outer tubular member **439**. Further, bends **436A/436B** in the flanges can assist in snapping the flanges into the apertures **438**.

In one embodiment, the inner shaft **404** is rotatable relative to the outer shaft of the insertion tool **400**, however, the inner shaft is axially fixed relative to the outer shaft.

Method claims are not limited to the order of the method steps claimed unless specifically so stated. Unless so specifically stated, the method steps may be performed in a different order and still fall within the scope of the claim.

Although the invention has been described herein with specific reference to preferred embodiments thereof, it will be appreciated by those skilled in the art that various modifications, deletions, and alterations may be made to such preferred embodiments without departing from the scope of the invention.

What is claimed:

1. An insertion tool, comprising:
 - an elongated outer shaft having an inner wall, a distal end, and a proximal end, including an outer shaft handle at the proximal end and a first flange, extending outside of the outer shaft distal end;
 - an elongated inner shaft having an outer wall, a distal end, and a proximal end, including an inner shaft handle at the proximal end and an engaging member at the inner shaft distal end;
 - at least a portion of the inner shaft being positioned within the outer shaft and the inner shaft being rotatable relative to the outer shaft and the inner wall directly adjacent the outer wall along the majority of the length of the inner wall, wherein the inner shaft is axially fixed relative to the outer shaft, wherein the first flange and engaging member are adapted to engage an anchor thereon, and the inner shaft is axially fixed relative to the outer shaft during such engagement to the anchor, wherein the anchor is adapted to be inserted into bone and includes a rotatable inner tubular member and an outer tubular member that are axially fixed relative one another prior to, during, and after engagement with the insertion tool, wherein the rotatable inner tubular member is adapted to wrap an engaged suture thread onto the rotatable inner tubular member thereby increasing tension on the suture thread and attached soft tissue, and wherein the first flange engages the outer tubular member and the engaging member engages the inner tubular member.
2. The insertion tool of claim 1, wherein the outer shaft distal end further includes a second flange.
3. The insertion tool of claim 2, wherein the first flange and the second flange have a bend.

4. The insertion tool of claim 3, wherein the first flange and the second flange are spring biased radially outwardly.
5. The insertion tool of claim 1, wherein the engaging member is a notch-shaped member.
6. The insertion tool of claim 1, wherein the engaging member is a blade-shaped member. 5
7. The insertion tool of claim 1, wherein the engaging member is a three-lobed member on a phillips-shaped four-lobed member.
8. The insertion tool of claim 1, wherein the engaging member is a square-shaped member. 10
9. The insertion tool of claim 1, wherein the engaging member is a hex-shaped member.
10. The insertion tool of claim 1, wherein the engaging member is a triangular-shaped member. 15
11. The insertion tool of claim 1, wherein the engaging member is a rectangular-shaped member.
12. The insertion tool of claim 1, wherein the first flange extends in a distal direction from the outer shaft distal end and the engaging member extends in a distal direction from the inner shaft distal end. 20

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